



Technische Universität München



Manuel Schiller <sup>1</sup>

Andreas Kern <sup>2</sup>

Alois Knoll <sup>1</sup>

**Real-time Electromagnetic Wave Propagation  
using OptiX for Simulation of  
Car-to-Car-Communication**  
NVIDIA GTC 2014, San Jose

<sup>1</sup> Robotics and Embedded Systems  
Department of Informatics  
Technische Universität München

<sup>2</sup> Audi Electronics Venture GmbH

# Agenda

- ▶ Motivation and Goals
- ▶ Simulation of Radio Wave Propagation
- ▶ Implementation in OptiX and CUDA
- ▶ Optimization of Ray Tracing Performance
- ▶ Outlook

# Motivation

- ▶ Vehicular Adhoc Networks (VANETs) will improve traffic safety, driving comfort and efficiency
- ▶ Advanced Driver Assistance Systems (ADAS) based on VANETs need to be tested thoroughly before deployment
- ▶ Real world testbeds
  - ▶ Are costly
  - ▶ Are not yet available
  - ▶ Do not deliver reproducible results
- ▶ Virtual test drives are already used to validate ADAS (see GTC 2012) and shall be enhanced for VANET simulation

# Signal Propagation in VANETs

- ▶ Signal propagation has **major impact** on ADAS **performance**
- ▶ Various wireless channel models exist:
  - ▶ Simple models (e.g. free space propagation)
  - ▶ Statistical models
  - ▶ Deterministic models
- ▶ Only deterministic models allow for a **site** and **situation specific** simulation of the wireless communication channel

# Requirements and Goals

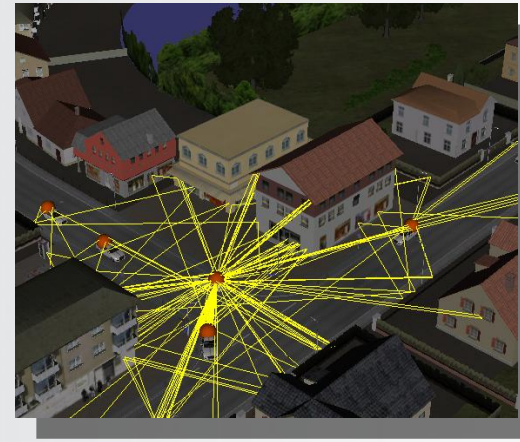
Simulate the wireless communication channel

- ▶ For **dynamic** and **detailed** scenes,
- ▶ Highly **accurate**,
- ▶ In **real time** (necessary for hardware-in-the-loop simulation)

in order to allow realistic testing of ADAS based on VANETs in virtual reality.

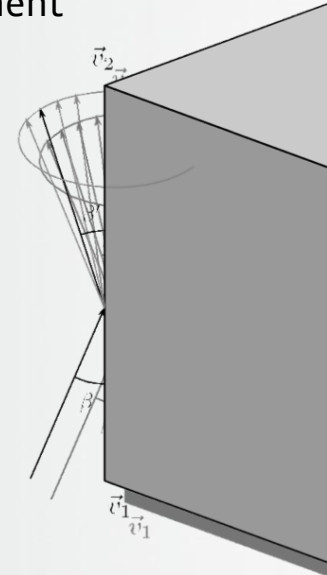
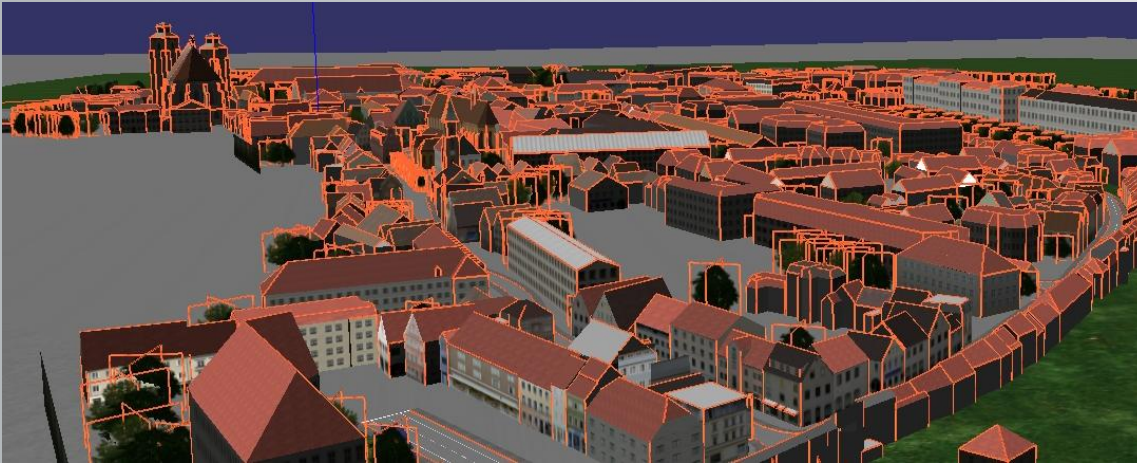
# Radio Wave Propagation using Ray Tracing

- ▶ Radio waves can be modeled as rays using
  - ▶ **G**eometrical **O**ptics and
  - ▶ the **U**nified **T**heory of **D**iffraction
- ▶ Ray tracing can be applied to find propagation paths of radio waves
- ▶ Brute-Force approach: Higher ray count = higher accuracy
- ▶ **S**tatic (e.g. buildings) and **d**ynamic obstacles (e.g. cars) block wave / ray propagation and cause **r**e**f**lection and **d**iffraction of waves
- ▶ Accurate 3D models of environment and cars are necessary



# Diffraction

- ▶ Diffraction at edges (e.g. of buildings) allows signal to be received even if there is no line-of-sight
- ▶ Important propagation phenomenon at intersections especially in urban environment
- ▶ Diffraction edges are detected in an automated offline preprocessing step



# Comparison with Image Rendering

- ▶ Multiple „lights“ = transmitting antennas
- ▶ Multiple „cameras“ = receiving antennas
- ▶ No image plane, rather a 360 degree field of view
- ▶ No approximations (like GI algorithms), we need the exact ray interactions for accurate calculation of amplitude and phase of the electromagnetic field
- ▶ Moving obstacles, therefore shadow regions cannot be precomputed



# Implementation

- ▶ We use **NVIDIA OptiX** for GPU Raytracing to find the propagation paths between transmitter and receiver
- ▶ High quality acceleration structures enable us to simulate highly **detailed** and **dynamic** scenes (carefully selecting the appropriate ones is crucial!)
- ▶ We employ different custom geometry types:
  - ▶ triangle meshes for 3D models
  - ▶ spheres for antennas
  - ▶ cylinders for diffraction edges
- ▶ OptiX allows us to concentrate on the actual wave propagation rather than on low-level ray tracing optimization
- ▶ Some (high-level) optimizations are still necessary

# Memory Management

- ▶ Every valid propagation path needs to be stored
- ▶ Worst case memory allocation for each ray:  $M = N_D^{L_D} \cdot L_R \cdot M_I$

$N_D$  New rays at diffraction (e.g. 100)

$L_D$  Maximum diffractions (e.g. 2)

$L_R$  Maximum reflections (e.g. 5)

$M_I$  Memory needed per interaction (e.g. 32 byte)

$$\Rightarrow M = 1.6 \text{ Megabyte}$$

4 GB GPU memory:

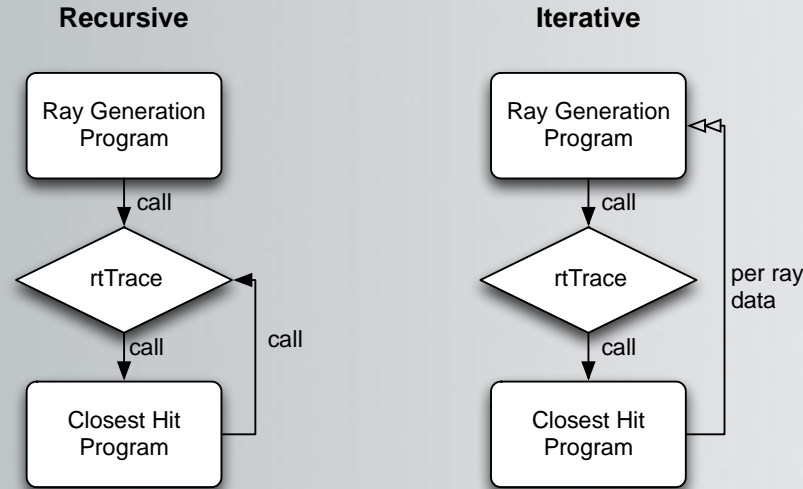
Only 2500 rays, but we rather need millions!

- ▶ Dynamic memory management:
  - ▶ Allocate a global buffer for all threads
  - ▶ When a path needs to be stored, atomic operations ensure serialized buffer access

# Improving Ray Tracing Performance

## Recursion vs. Iteration

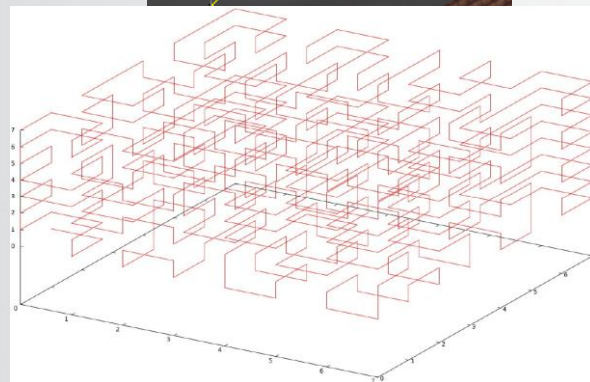
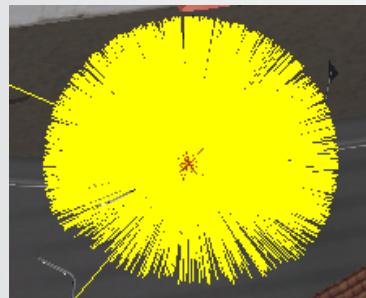
- ▶ Max. reflections / diffractions can lead to very high recursion depths
- ▶ Iterative Ray Tracing is **up to 10 % faster** than recursive approach



# Improving Ray Tracing Performance

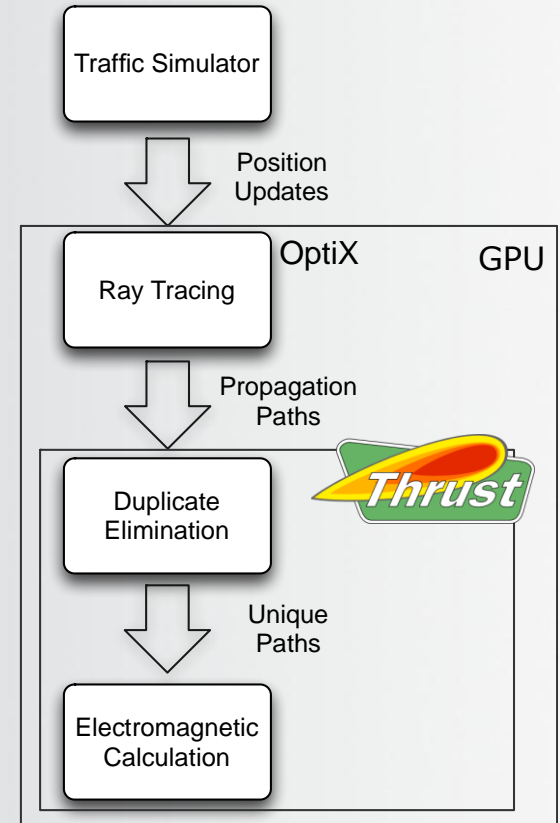
## Ray reordering

- ▶ Naive approach:
  - ▶ Sample N random directions on sphere surface, then trace them immediately
  - ▶ works, but bad ray coherence (memory access and divergence)
- ▶ Better:
  - ▶ Sort random directions before tracing using space filling curve (Hilbert curve, Z-curve)
  - ▶ Outperforms naive approach by **up to 100 %**

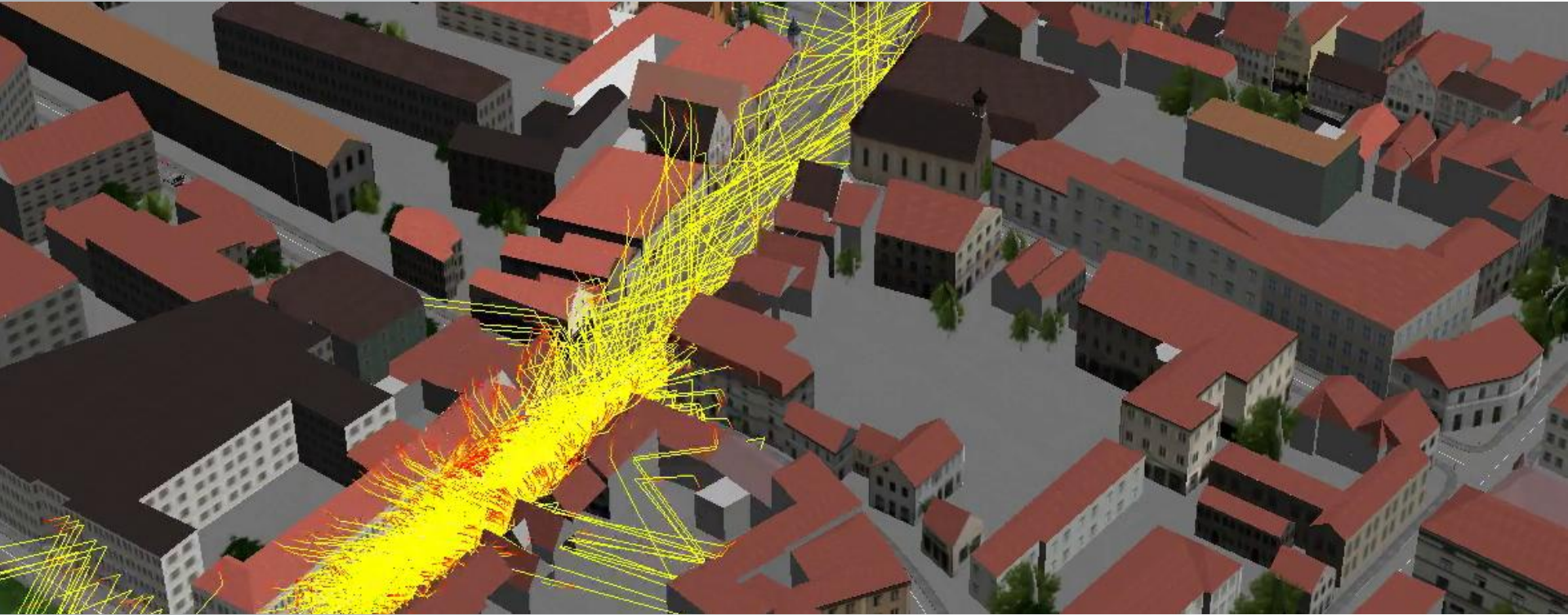


# Wave Propagation Simulation Pipeline

- ▶ No on-the-fly „shading“ of rays, because only few rays arrive
- ▶ Only geometric information of propagation path is stored
- ▶ Electromagnetic field calculation is applied in a postprocessing step for each detected propagation path
- ▶ Postprocessing is also done on GPU using Thrust:
  - ▶ No memory copying needed thanks to OptiX-CUDA interop
  - ▶ Parallel iterating over propagation paths
  - ▶ Parallel reduce-by-key to sum up contribution of different propagation paths per receiving antenna



# Video



# Outlook

- ▶ Coupling of ray tracing results with network simulator
- ▶ Simulation of MIMO antenna systems
- ▶ Exploration of Multi-GPU performance
- ▶ Exploitation of frame coherence

**Thank you very much.**

**Contact:**

Manuel Schiller, Technische Universität München

[manuel.schiller@in.tum.de](mailto:manuel.schiller@in.tum.de)