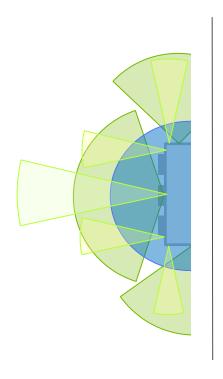
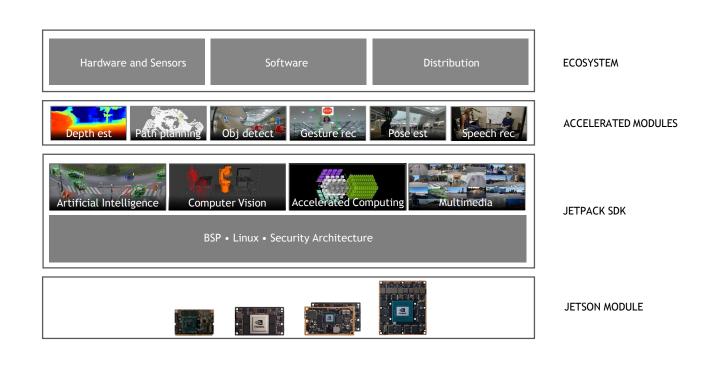




# NVIDIA JETSON SOFTWARE-DEFINED AUTONOMOUS MACHINES

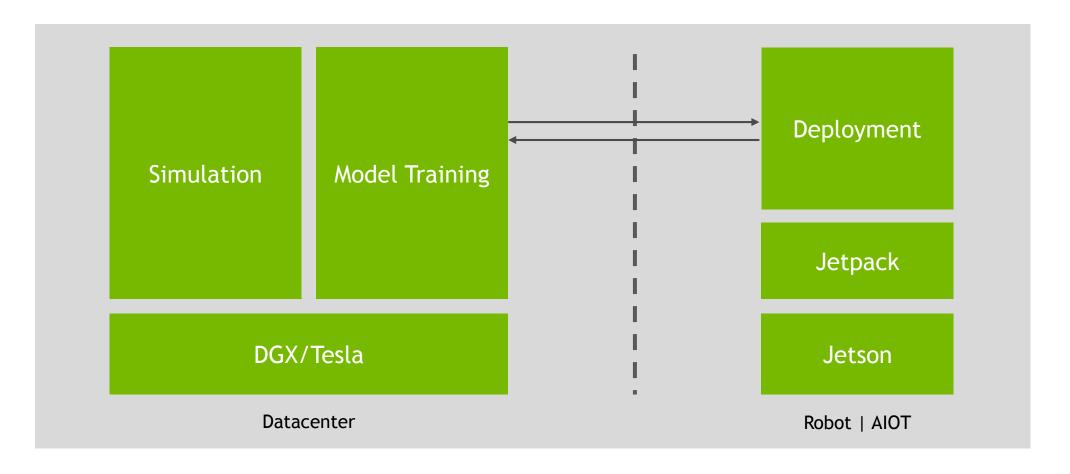
Powerful and efficient AI, CV, HPC | Rich Software Development Platform Open Platform | 250K Developers





# **NVIDIA AI PLATFORM**

#### From data center to machines



# THE JETSON FAMILY

#### From AI at the Edge to Autonomous Machines



JETSON NANO 5 - 10W 0.5 TFLOPS (FP16) 45mm x 70mm \$129



JETSON TX2 Series (TX2, TX2 4GB, TX2i\*) 7.5 - 15W\* 1.3 TFLOPS (FP16) 50mm x 87mm Starting at \$249



JETSON AGX XAVIER Series (AGX Xavier 8GB, AGX Xavier) 10 - 30W 5.5 - 11 TFLOPS (FP16) 20 - 32 TOPS (INT8) 100mm x 87mm Starting at \$599

Fully autonomous machines

Al at the edge

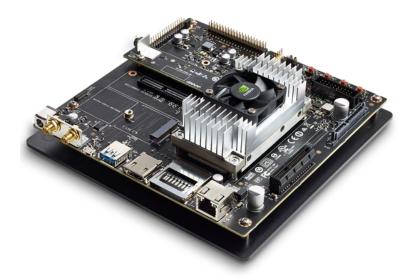
#### Multiple devices - Same software

### JETSON DEVELOPER KITS

For Engineers, Makers, and Learners



JETSON NANO 5W | 10W 0.5 TFLOPS (FP16) \$99



JETSON TX2 7.5W | 15W 1.3 TFLOPS (FP16) \$399 (\$299 EDU)



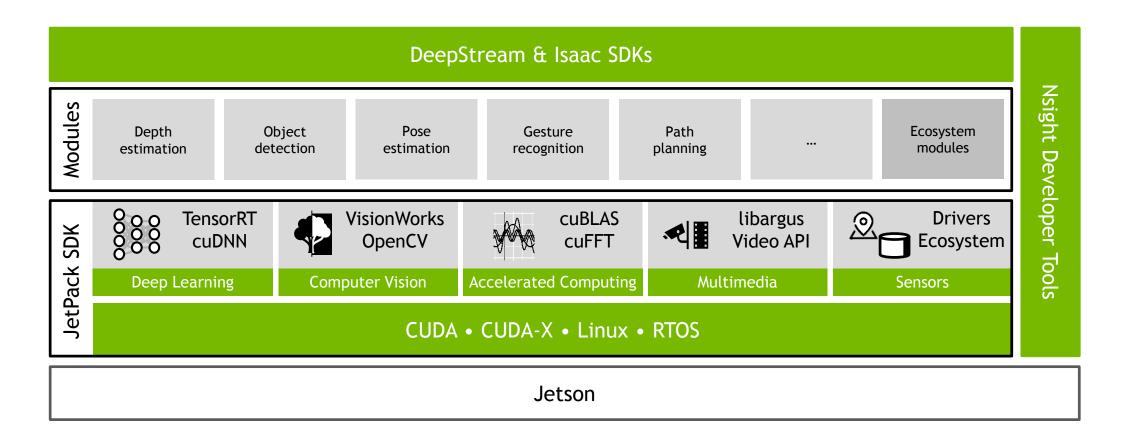
JETSON AGX XAVIER

10 | 15W | 30W

11 TFLOPS (FP16) | 32 TOPS (INT8)
\$699

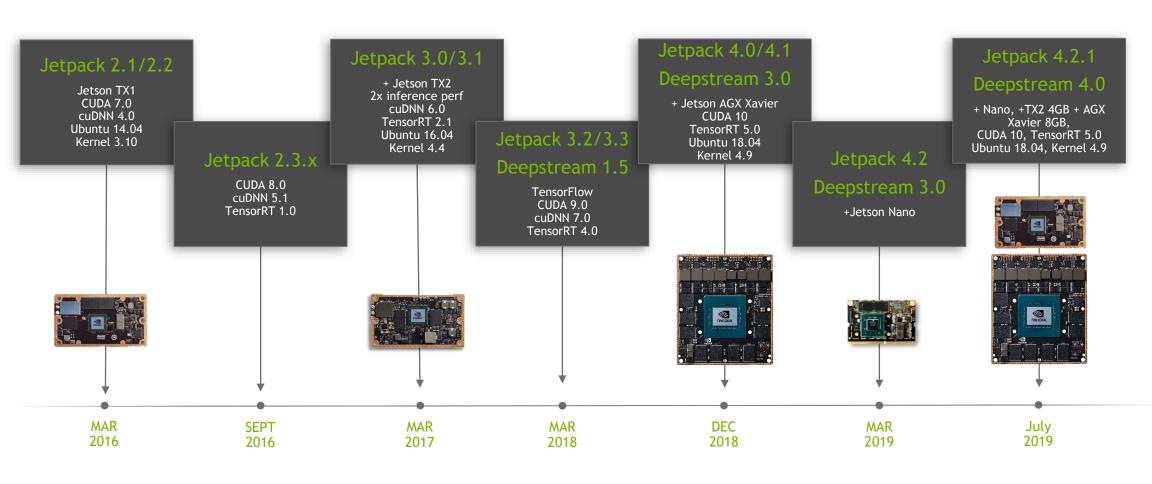
#### Multiple developer kits - Same software

# **JETSON SOFTWARE**



Jetson software: developer.nvidia.com/jetson

# **CONTINUOUS SOFTWARE INVESTMENT**



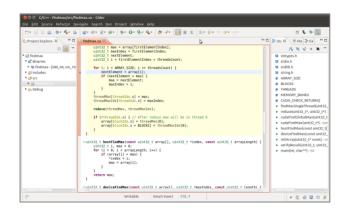
#### JETSON DEVELOPER TOOLS

#### Comprehensive tool suite to accelerate development

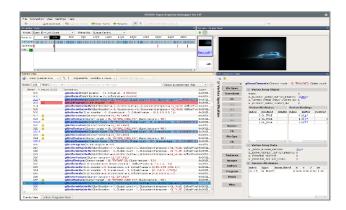
System wide application tuning and optimization

Workload balancing across GPU, CPU, DLA

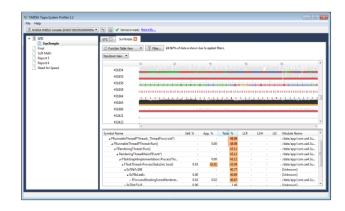
Multi-platform development



**CUDA-aware editor** 



CPU/GPU debugger Compute and graphics



Visual profiler and system trace

Develop → Profile → Analyze → Optimize

### **JETSON ECOSYSTEM**

**DISTRIBUTION** 





**MACNICA** 



HANCOM MDS







**SOFTWARE** 









**HW AND SENSORS** 





# **JETSON SUCCESS STORIES**

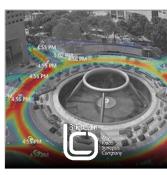












Industrial

Aerospace/Defense

Construction

Agriculture

Healthcare

**Smart City** 













Retail

Logistics

Delivery

Inspection

Service

Collaboration

Ser

## **JETSON - START NOW**



#### JETSON DEVELOPER KIT

Start developing now Starting at \$99 developer.nvidia.com/ buy-jetson



#### TWO DAYS TO A DEMO

Create your first demo today developer.nvidia.com/ embedded/twodaystoademo



#### **DEEP LEARNING INSTITUTE**

Training • Labs Nanodegrees nvidia.com/DLI



#### GTC

Largest event for GPU developers

gputechconf.com

# **JETSON - START NOW**



Home

#### Meet Jetson, the Platform for AI at the Edge.

NVIDIA Jetson is the world's leading embedded AI computing platform. Its high-performance, low-power computing for deep learning and computer vision makes it possible to build software-defined autonomous machines.

The Jetson platform includes small form-factor Jetson modules with GPU-accelerated parallel processing, the JetPack SDK with developer tools and comprehensive libraries for building Al applications, along with an ecosystem of partners with services and products that accelerate development.

**AUTONOMOUS MACHINES** 

https://developer.nvidia.com/embedded-computing



# **ISAAC**







Isaac Robot Engine Isaac Sim Isaac Gym

Isaac Robot Engine - Modular robot framework | Isaac Sim - Virtual robotics laboratory
Isaac Gym - Reinforcement learning simulator | Isaac Robot Apps - Kaya, Carter and Link

Available at developer.nvidia.com/isaac-sdk

### **NVIDIA ISAAC ROBOTICS SOFTWARE**

ISAAC SDK

a collection of APIs and tools to develop robotics algorithm software and runtime framework with fully accelerated libraries.

ISAAC GEMS

Isaac Intelligent Machine Acceleration applications, a collection of NVIDIA-developed robotics algorithm software.

ISAAC SIM

a highly realistic virtual simulation environment for developers to train autonomous machines and perform hardware-in-the-loop testing with Jetson Xavier.

# WHAT IS ROBOTICS

https://en.wikipedia.org/wiki/Robotics

Sensing/Perception

Locomotion/Navigation

Manipulation

Actuation

### **CHALLENGES**

Large Established Players - Specialized HW and SW

Startups - Open Source SW

All - AI-powered Robots

### WHY NVIDIA ISAAC™?

#### Three Key Benefits

# ACCELERATE DEVELOPMENT OF ROBOTS

using a hardware + software platform built for robotics

#### DEPLOY PRODUCTION-GRADE ROBOTS AT SCALE

using an open and extensible platform for industrial, service, and commercial robots

#### **BUILD SMARTER ROBOTS**

leveraging AI, computer vision, simulation, and other algorithms accelerated by NVIDIA compute platforms

Isaac is a platform for robot development and simulation that's optimized for NVIDIA hardware platforms

# ISAAC ROBOTICS PLATFORM

#### Isaac Downloads

Download the NVIDIA® Isaac SDK and related files below.

| Item                         | Description   | Link       |
|------------------------------|---|------------|
| Isaac SDK 2019.1             | NVIDIA® Isaac SDK 2019.1 sources and pre-compiled packages.   | Download > |
| Isaac SDK nightly 2019-05-28 | Nightly build of NVIDIA® Isaac SDK 2019-05-28 sources and pre-compiled packages.  | Download > |
| IsaacSim nightly 2019-05-29  | Nightly build of NVIDIA® Isaac SIM 2019-05-28 sources and pre-compiled packages.  | Download > |
| Kaya Robot Reference Design  | Kaya robot reference design and 3D printable parts. Detailed instructions are available in the Isaac developer guide documentation. | Download > |
| Isaac SDK Developer Guide    | Documentation, developer guide for NVIDIA® Isaac Software Development Kit (SDK).  | View >     |
| Isaac Sim Content XML        | NVIDIA® Isaac Sim sources and content. Setup instructions can be found in the Isaac Sim Developer Guide.                            | Download > |
| Kaya Sim App for Isaac SDK   | Kaya app add-on for the Isaac SDK. Quick start instructions can be found in the Isaac Sim Developer Guide.                          | Download > |
| Isaac Sim Developer Guide    | Documentation, developer guide for NVIDIA® Isaac Sim.   | View >     |

 $\underline{https:/\!/developer.nvidia.com/isaac/downloads}$ 

# INVITATION TO ECOSYSTEM

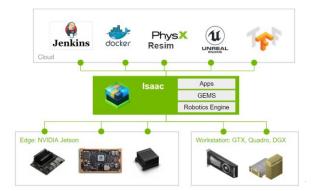
To use Isaac platform to make it easy for robotics developers

Deploy AI powered robots at scale.





Simulate in our Isaac Sim platform.



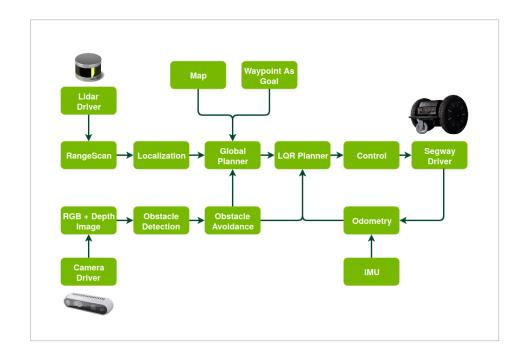
Deliver latest software to the Isaac users using continuous integration.



### ISAAC ROBOT ENGINE

#### Component-Based Design

- Framework to build modular robotics applications
- The power to drive high-perf image processing/DL applications
- Computational graphs and entity component system
- Behavior tree
- Seamless compatibility with NVIDIA®Jetson AGX™/TX2/Nano and NVIDIA dGPU



### ISAAC ROBOT ENGINE

#### Visualization

- ISAAC SIGHT:
  - API to create variable plots and visualize data in 2D or 3D renderings
- ISAAC WEBSIGHT:
  - Web-based front end to look at data provided by the Sight API





### PERCEPTION CAPABILITIES

- Fiducial detection system using AprilTag detection
- Path perception using DNN-based path segmentation\*
- Obstacle perception using DNNbased object detection
- Superpixels









<mark> Π</mark>VIDIA.

# **MAPPING**

LIDAR-based map creation Map annotation Map editor

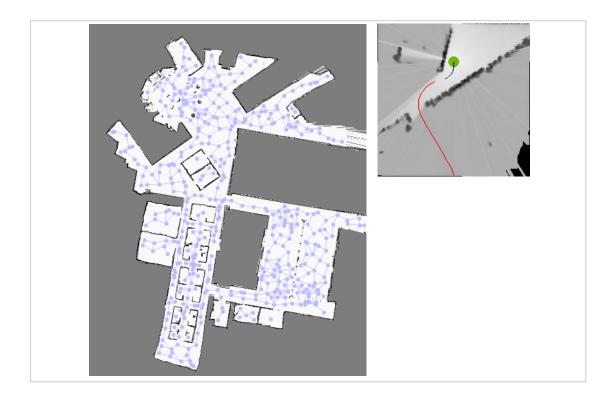
Accurate modification

gmapping and Cartographer



# **NAVIGATION**

- LIDAR-based localization
- LIDAR-based global localization
- Global path planning
- Trajectory planning (LQR)

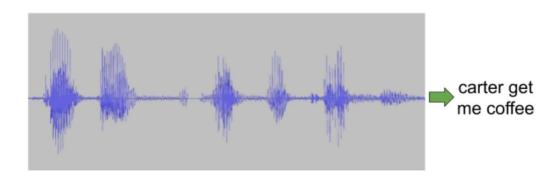


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### IX

#### **Human Machine Interaction**

- ListeNet: Detection to recognize a trained set of voice commands
- Gesture recognition
- Face detection/recognition
- and more





### ISAAC REFERENCE DESIGNS

#### For Indoor Logistics (Carter) and Getting Started (Kaya)

#### CARTER:

Carter is an Isaac SDK reference robot platform for autonomous indoor delivery and logistics based on the Jetson AGX Xavier platform.

#### **KAYA**:

Kaya is a small robot reference platform to get started with the Isaac SDK; based on Jetson Nano.





### ML/DL ACCELERATION

#### Reference DNNs

- StereoDNN (stereo depth)
- UNet (path segmentation)
- ListeNet (voice)
- Yolo (object detection)
- Support for TensorFlow, Keras, Python bindings and NVIDIA TensorRT for DNN inference

#### ISAAC REFERENCE DESIGNS

#### Sample Applications

#### CARTER APPS:

Use a given waypoint as a goal to travel to (Map Waypoint)

Use a specific place in the building as a goal to travel to (Pose)

Travel a predetermined route (Patrol mode)

Travel from one waypoint to another randomly chosen waypoint (Random)

#### KAYA APPS:

Detect and follow an AprilTag (Follow-me)

Map Kaya's environment using stereo camera and a joystick (Mapping)

Detect the objects using DNN and classify objects

# **SIMULATION**

#### Robot Simulation to Test Navigation, Manipulation, and Perception

- Domain randomization
- Support for Unity and UnReal game engines
- Simulation of

Robot dynamics

Sensors (camera, LIDAR, IMU)

Different environments

Agents around robots (dynamic environment)



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# **ISAAC**

#### Where to get it from and Product Support

DEVZONE

https://developer.nvidia.com/isaac-sdk

FORUMS

https://devtalk.nvidia.com/default/board/374/isaac/

