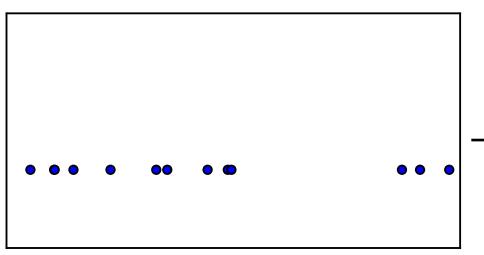
MedGAN ID-CGAN CoGAN LR-GAN CGAN IcGAN b-GAN LS-GAN AffGAN LAPGAN DiscoGANMPM-GAN AdaGAN AMGAN iGAN LSGAN InfoGAN CatGAN Generative Adversarial Networks Ian Goodfellow, Staff Research Scientist, Google Brain MIX+GAN McGAN NVIDIA GPU Technology Conference DR-GAN C-RNN-GAN MGAN San Jose, California 2017-05-09 GoGAN FF-GAN C-VAE-GAN DCGAN AC-GAN CCGAN MAGAN 3D-GAN BiGAN DualGAN GAWWN CycleGAN **GP-GAN Bayesian GAN** AnoGAN EBGAN DTN ALI MARTA-GAN f-GAN A++ MAD-GAN AL-CGAN MalGAN BEGAN ArtGAN

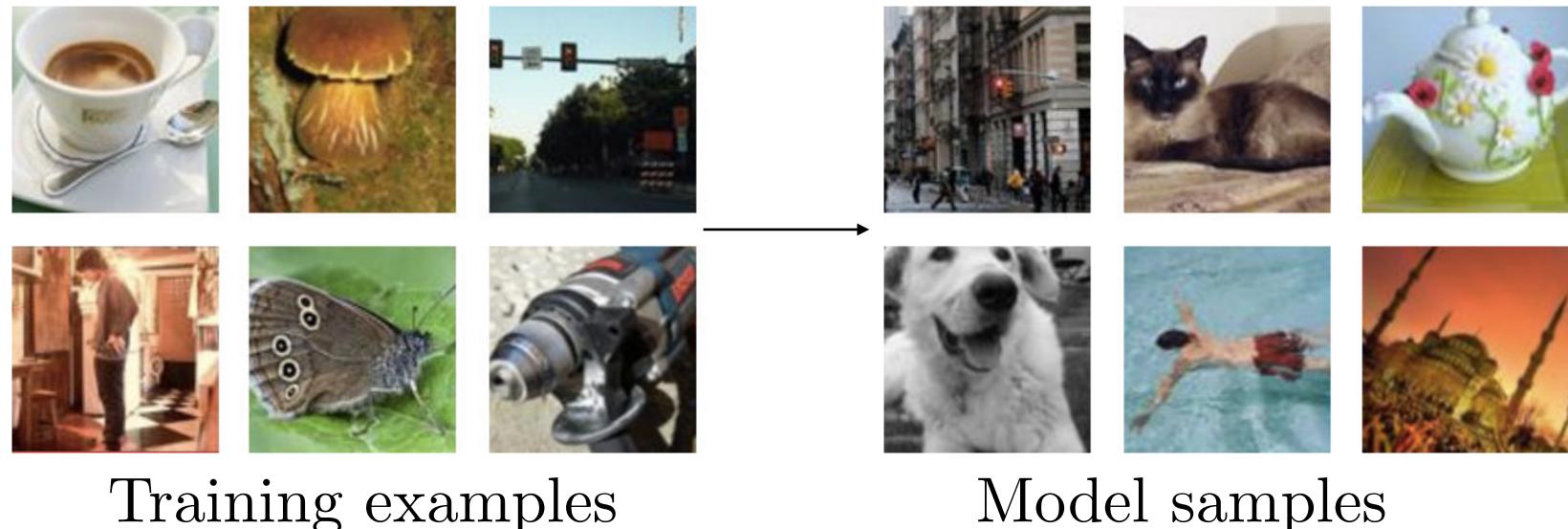


Generative Modeling

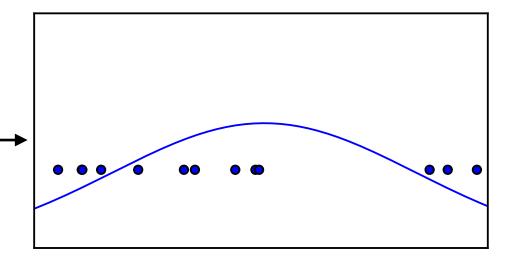
• Density estimation



• Sample generation

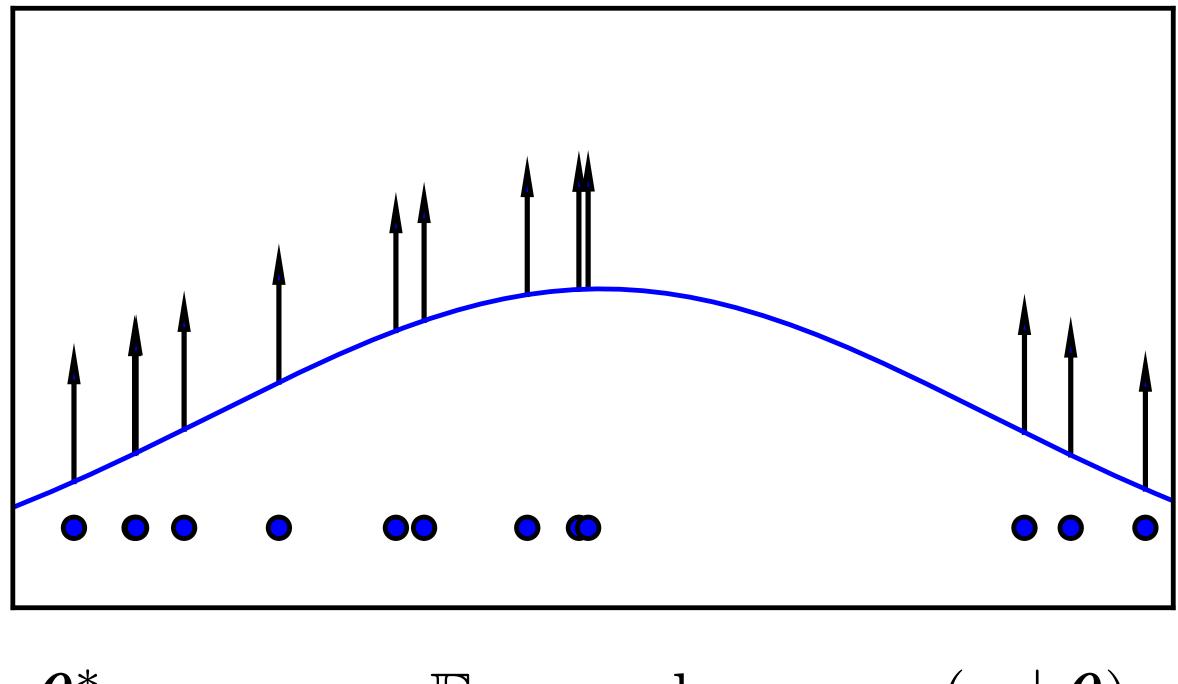


Training examples





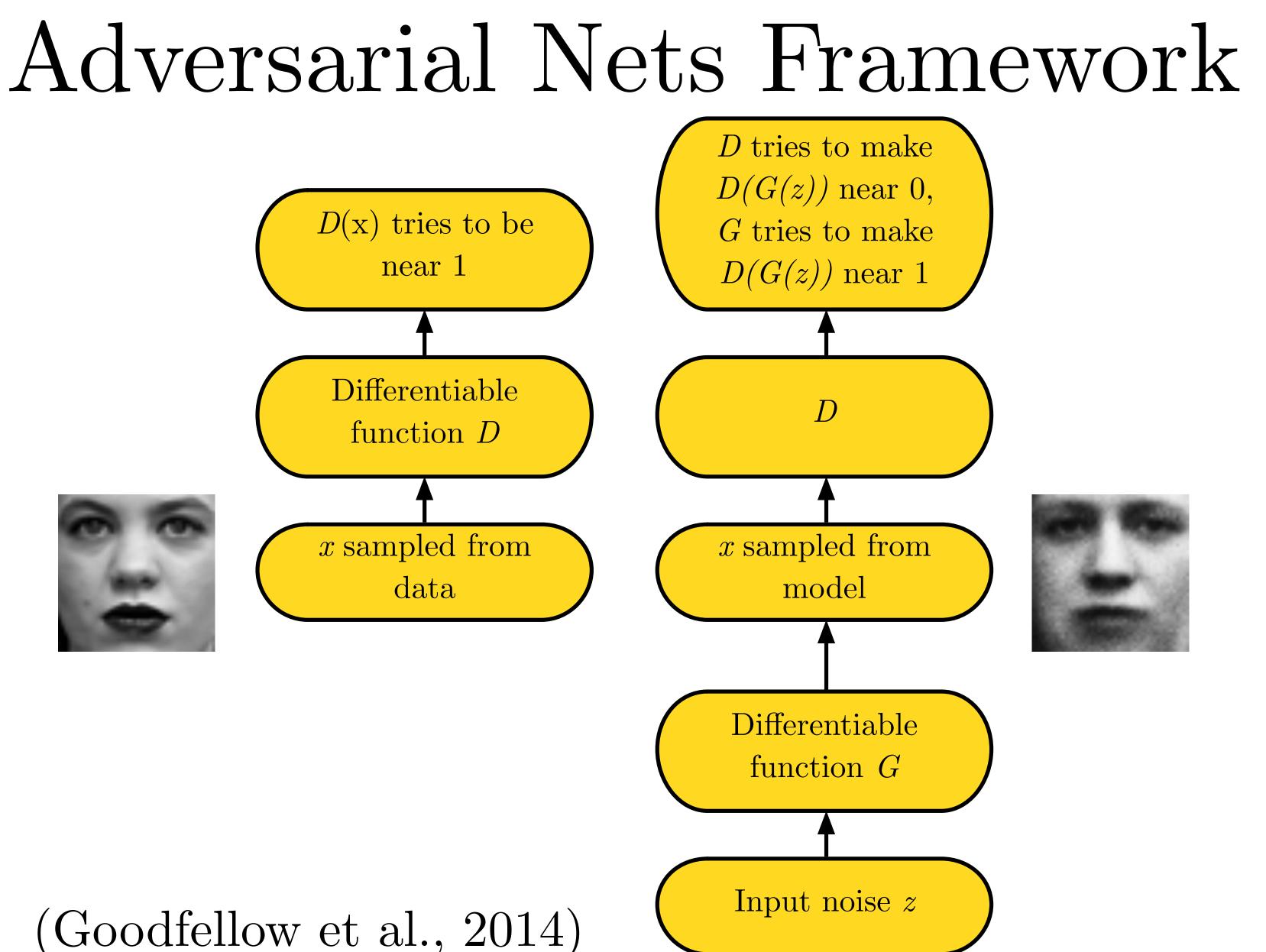
Maximum Likelihood



θ

 $\boldsymbol{\theta}^* = rg \max \mathbb{E}_{x \sim p_{\text{data}}} \log p_{\text{model}}(\boldsymbol{x} \mid \boldsymbol{\theta})$





(Goodfellow et al., 2014)



- Simulated environments and training data
- Missing data
 - Semi-supervised learning
- Multiple correct answers
- Realistic generation tasks
- Simulation by prediction
- Solve inference problems
- Learn useful embeddings



ΑΙ



OBSESSIONS

Q

GANs for simulated training data Unlabeled Real Images







Synthetic





Refined

(Shrivastava et al., 2016)



- Simulated environments and training data
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What is in this image?

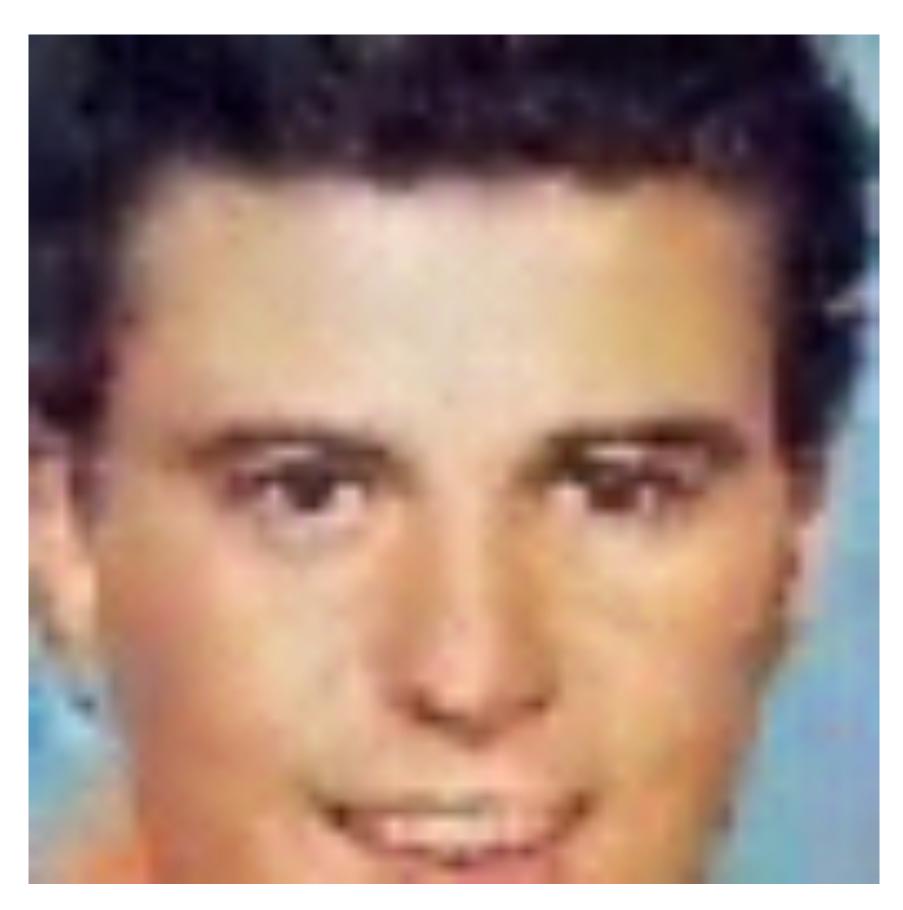




(Yeh et al., 2016)



Generative modeling reveals a face



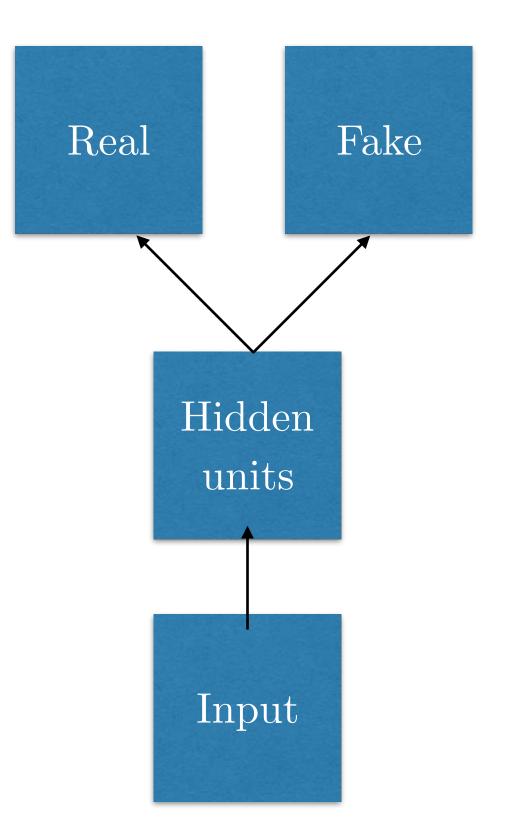


(Yeh et al., 2016)



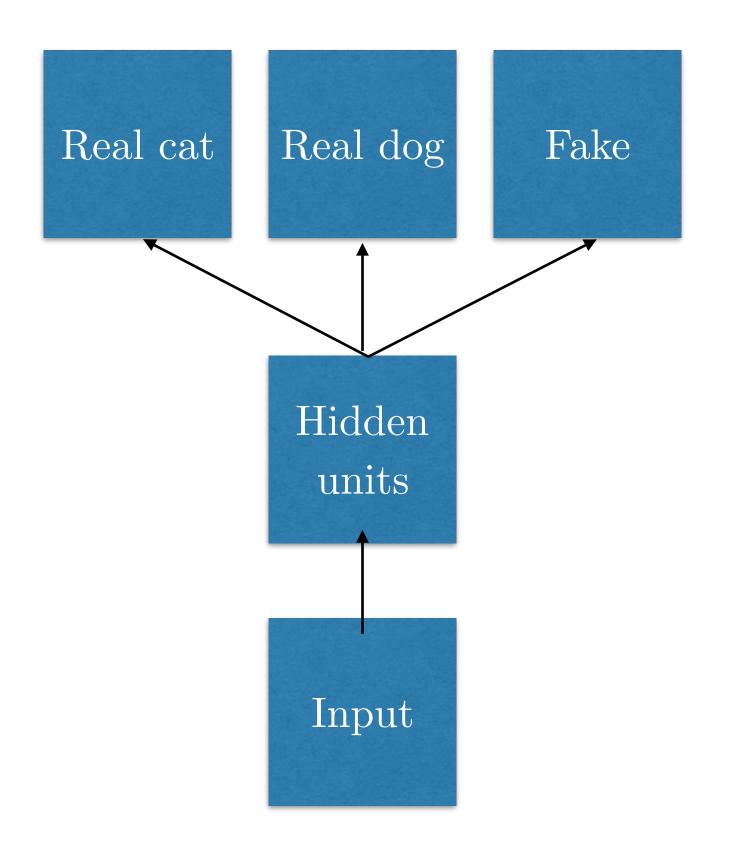
- Simulated environments and training data
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(Odena 2016, Salimans et al 2016)

Supervised Discriminator





Semi-Supervised Classification

20

Model

DGN [21] Virtual Adversarial [22] CatGAN [14] Skip Deep Generative Model [23] Ladder network [24] Auxiliary Deep Generative Model [23] 1677 ± 4 Our model 1134 ± 4 Ensemble of 10 of our models

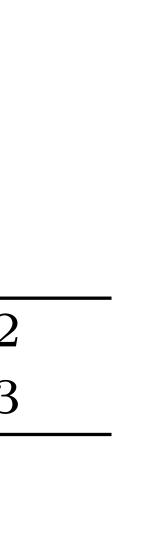
MNIST (Permutation Invariant)

Number of incorrectly predicted test examples

for a given number of labeled samples

| | 50 | 100 | 200 |
|-----|---------------|--------------|--------------|
| | | 333 ± 14 | |
| | | 212 | |
| | | 191 ± 10 | |
| | | 132 ± 7 | |
| | | 106 ± 37 | |
| | | 96 ± 2 | |
| 152 | 221 ± 136 | 93 ± 6.5 | 90 ± 4.2 |
| 45 | 142 ± 96 | 86 ± 5.6 | 81 ± 4.3 |

(Salimans et al 2016)



Semi-Supervised Classification

CIFAR-10

| Model | Test error rate for a given number of labeled samples | | | |
|------------------------------|--|--------------------|--------------------|--------------------|
| | 1000 | 2000 | 4000 | 8000 |
| Ladder network [24] | | | $20.40 {\pm} 0.47$ | |
| CatGAN [14] | | | $19.58 {\pm} 0.46$ | |
| Our model | $21.83{\pm}2.01$ | $19.61 {\pm} 2.09$ | $18.63 {\pm} 2.32$ | 17.72 ± 1.82 |
| Ensemble of 10 of our models | $19.22 {\pm} 0.54$ | $17.25 {\pm} 0.66$ | $15.59 {\pm} 0.47$ | $14.87 {\pm} 0.89$ |

Au



SVHN

| Model | Percentage of incorrectly predicted test examples | | |
|-------------------------------------|---|--------------------|-----------------|
| | for a given number of labeled samples | | |
| | 500 | 1000 | 2000 |
| DGN [21] | | $36.02 {\pm} 0.10$ | |
| Virtual Adversarial [22] | | 24.63 | |
| uxiliary Deep Generative Model [23] | | 22.86 | |
| Skip Deep Generative Model [23] | | $16.61 {\pm} 0.24$ | |
| Our model | 18.44 ± 4.8 | 8.11 ± 1.3 | 6.16 ± 0.58 |
| Ensemble of 10 of our models | | 5.88 ± 1.0 | |
| | | | |

(Salimans et al 2016)

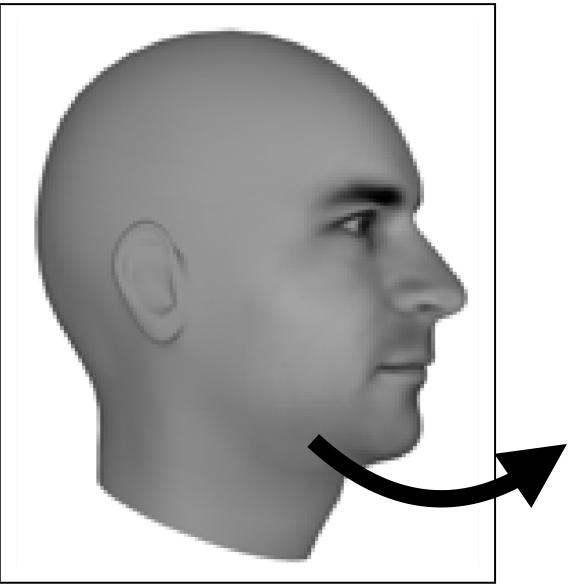


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Next Video Frame Prediction





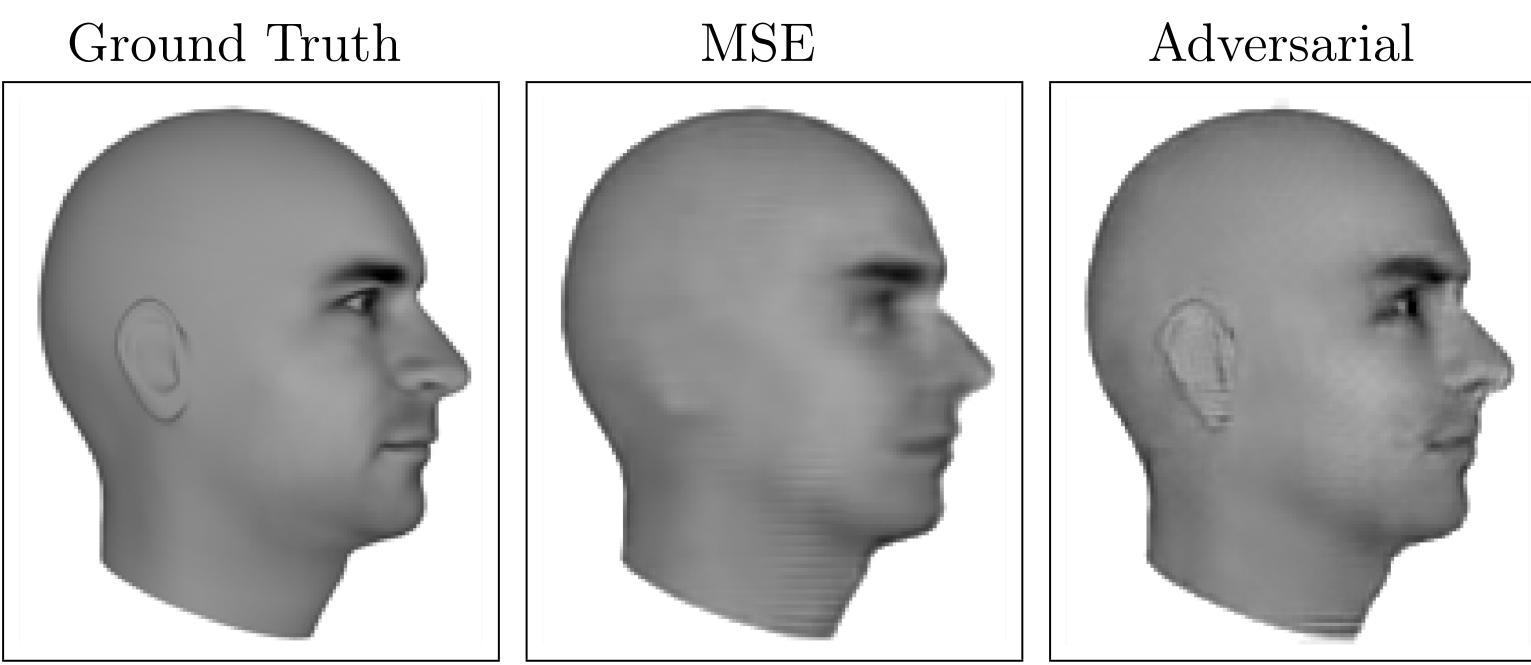
What happens next?

(Lotter et al 2016)

Ground Truth



Next Video Frame Prediction





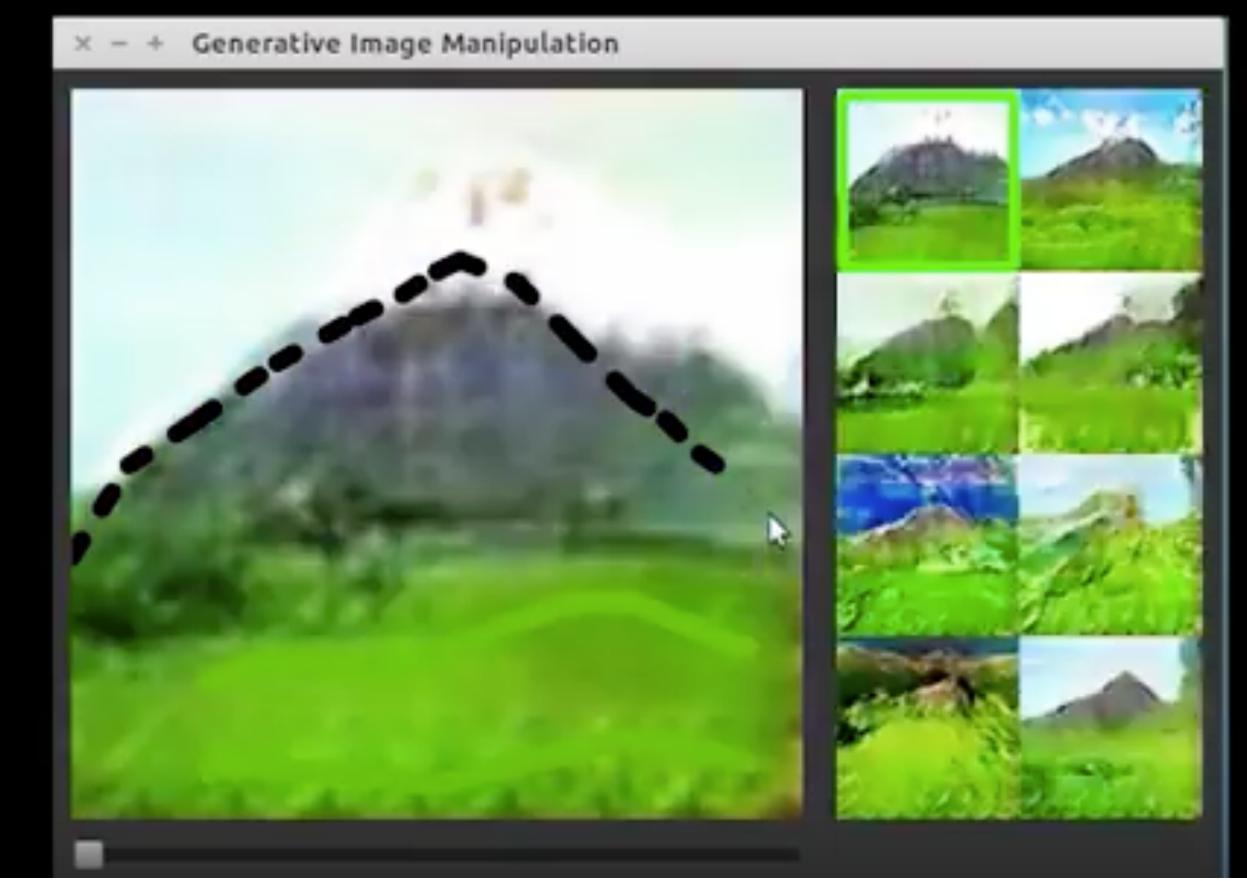
(Lotter et al 2016)



- Simulated environments and training data
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iGAN



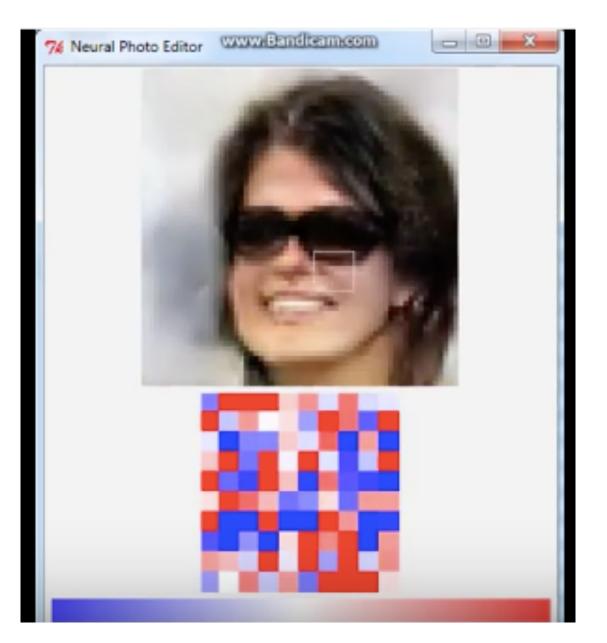


youtube

(Zhu et al., 2016)



Introspective Adversarial Networks



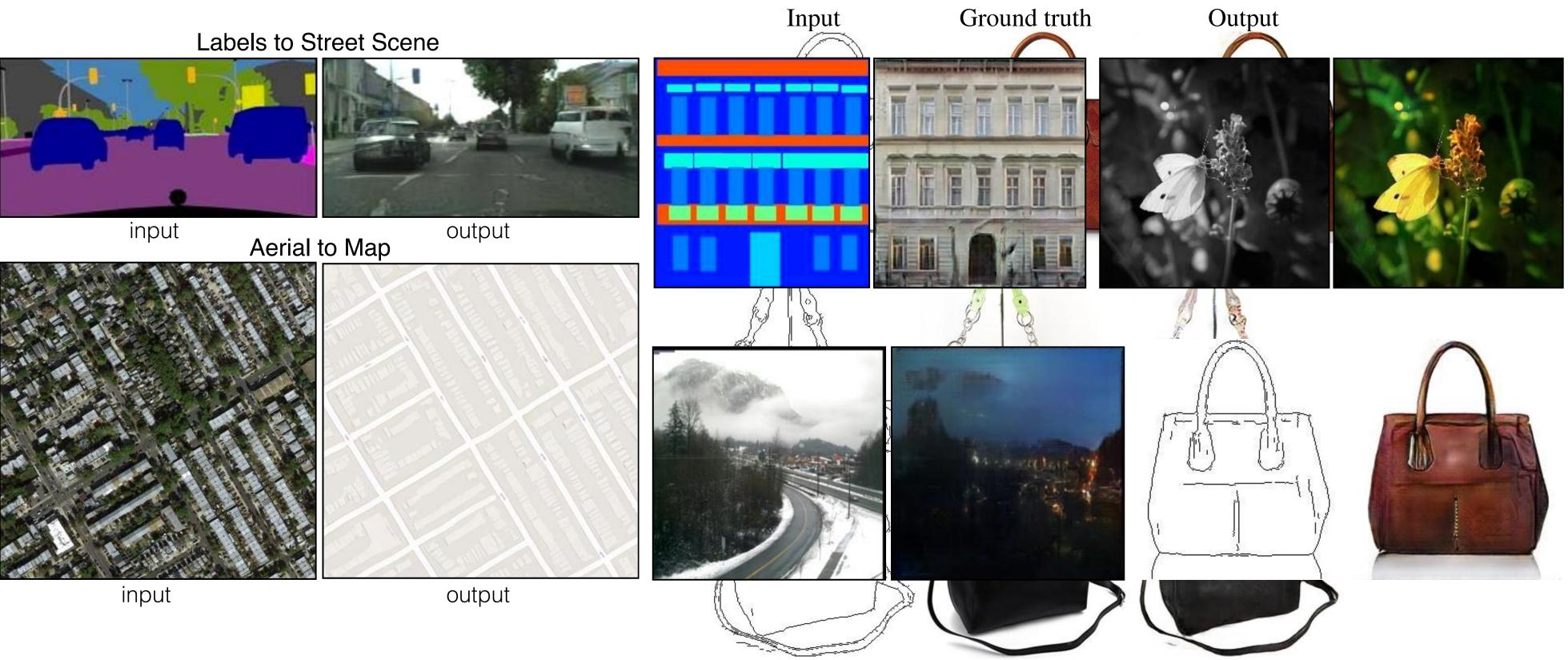


youtube

(Brock et al., 2016)



Image to Image Translation









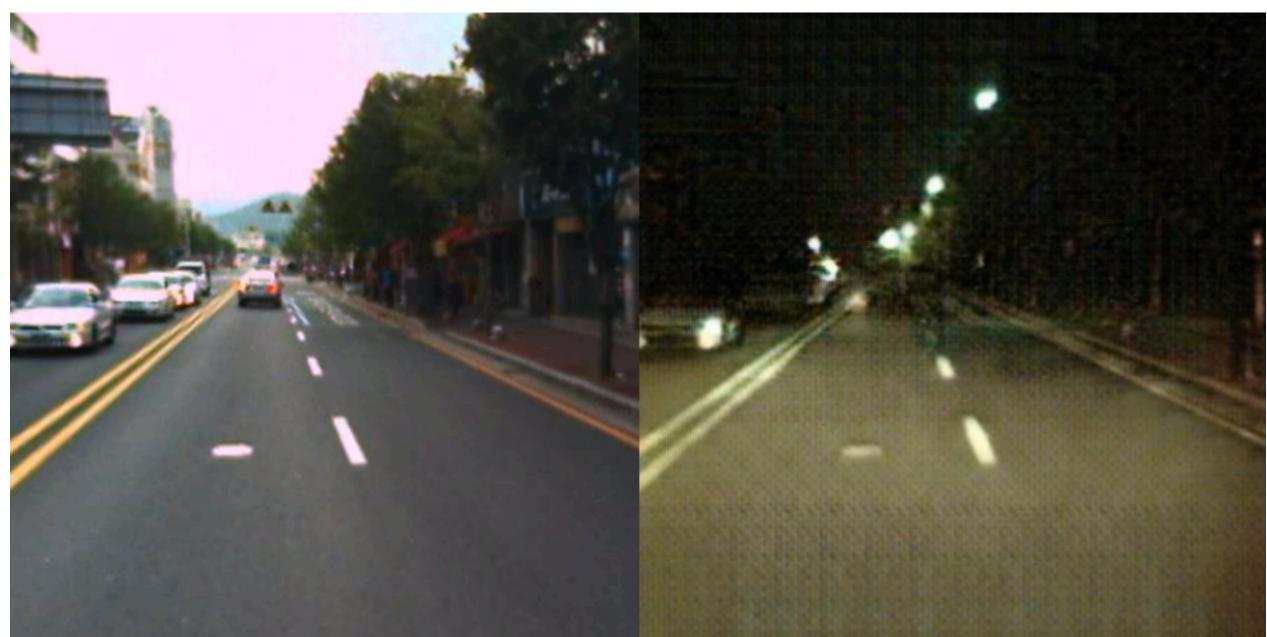


(Isola et al., 2016)



Unsupervised Image-to-Image Translation







Day to night

(Liu et al., 2017)



CycleGAN





(Zhu et al., 2017)



Text-to-Image Synthesis

This bird has a yellow belly and tarsus, grey back, wings, and brown throat, nape with a black face









(Zhang et al., 2016)

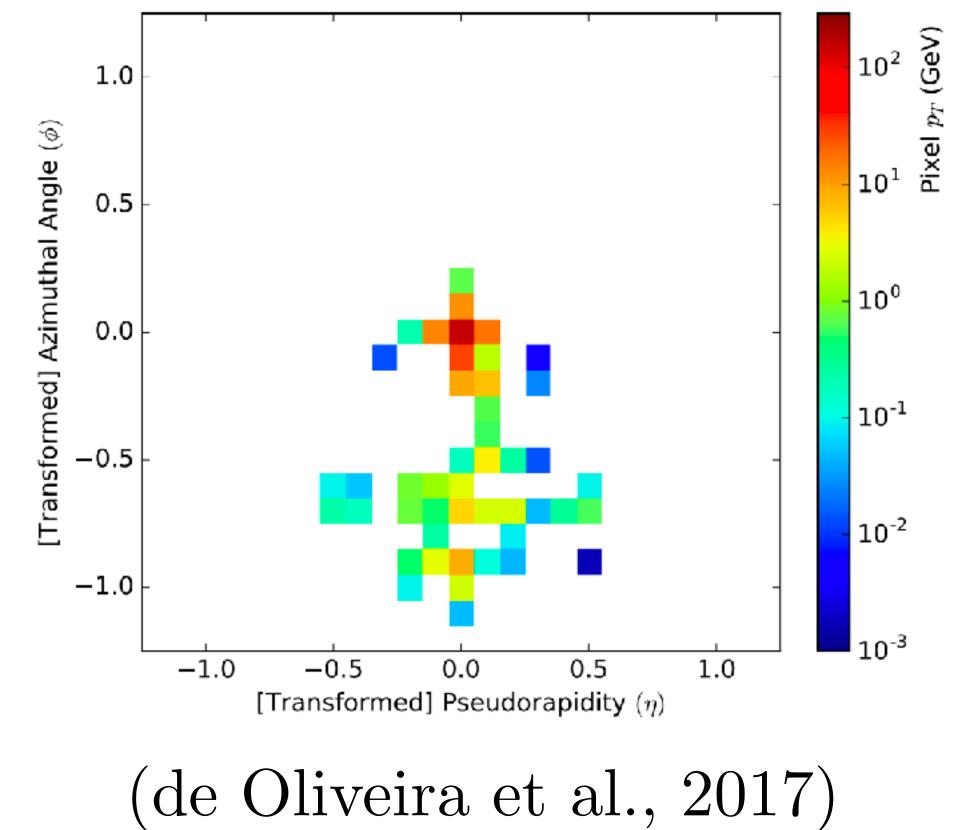


- Simulated environments and training data
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Simulating particle physics

Save millions of dollars of CPU time by predicting outcomes of explicit simulations

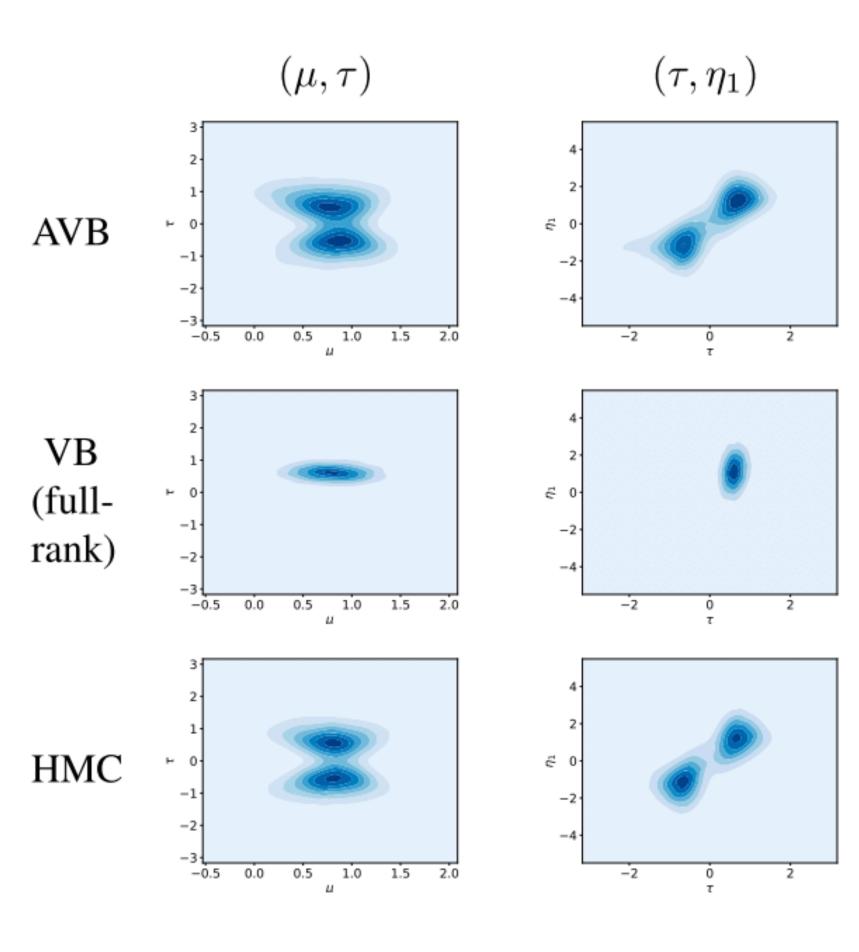




- Simulated environments and training data
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Adversarial Variational Bayes



(Mescheder et al, 2017)



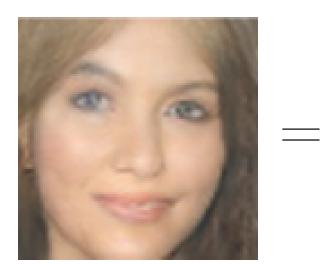
- Simulated environments and training data
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Vector Space Arithmetic







Man Man with glasses

(Radford et al, 2015)

Woman



Woman with Glasses



Learning interpretable latent codes controlling the generation process



(a) Azimuth (pose)



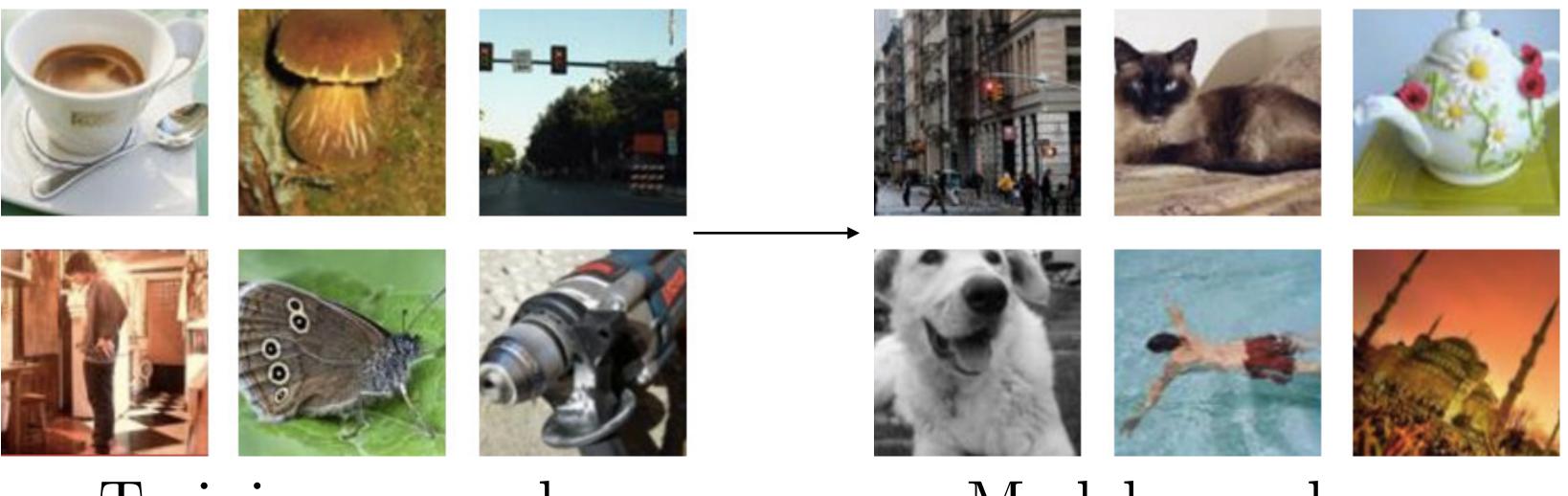
(c) Lighting

(b) Elevation

(d) Wide or Narrow

InfoGAN (Chen et al 2016)









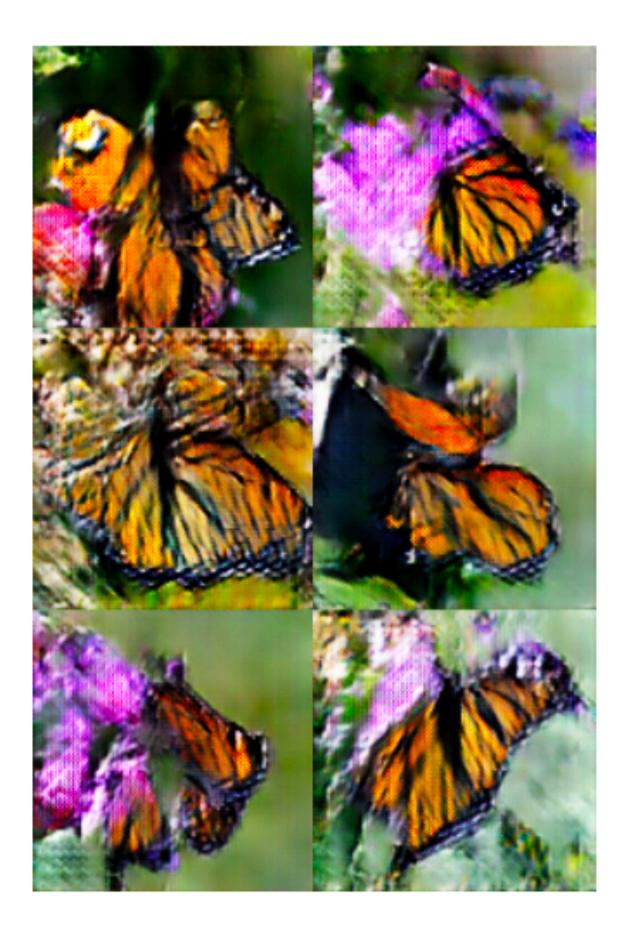


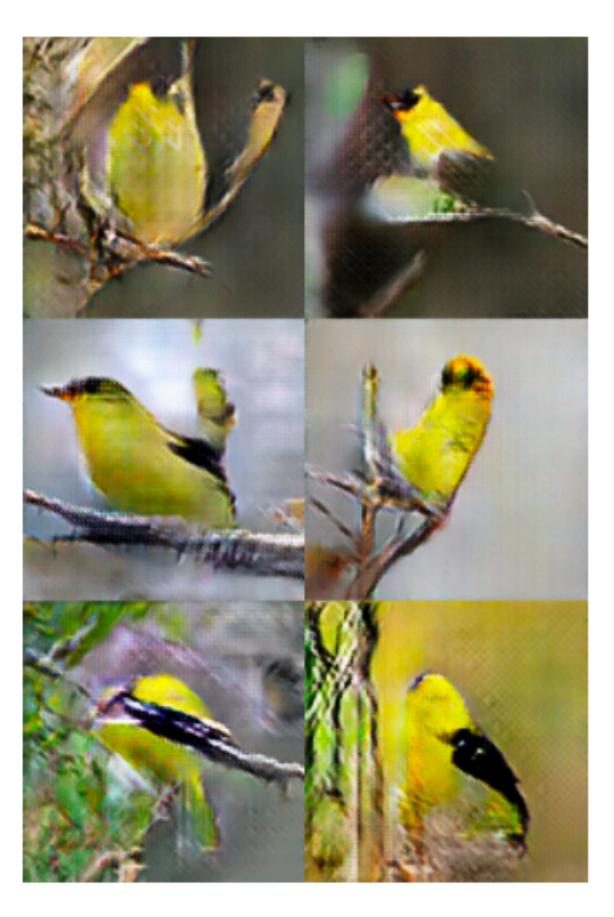
Training examples

How long until GANs can do this?

Model samples



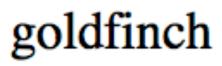




monarch butterfly

(Odena et al., 2016)

AC-GANs

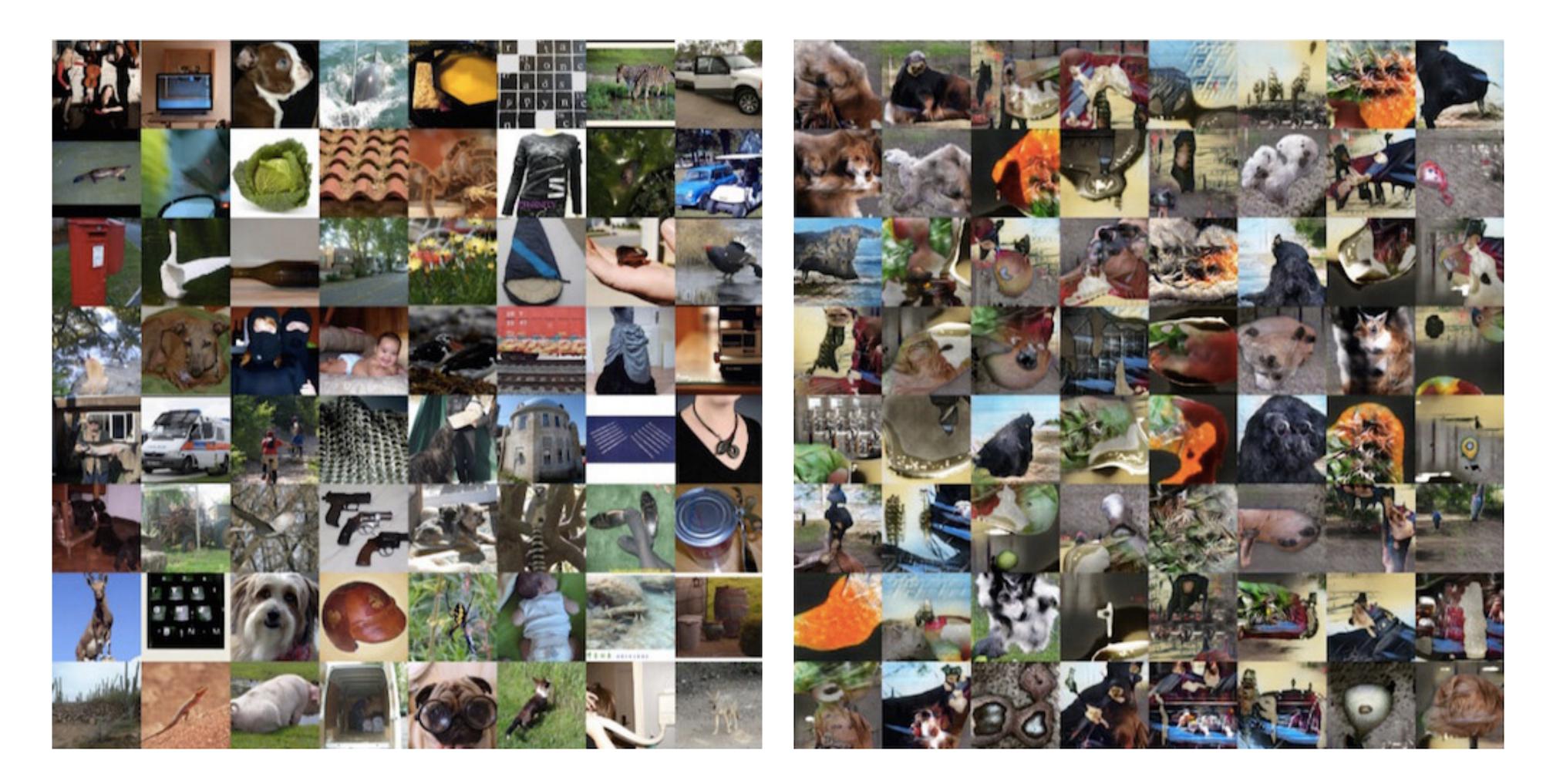




daisy



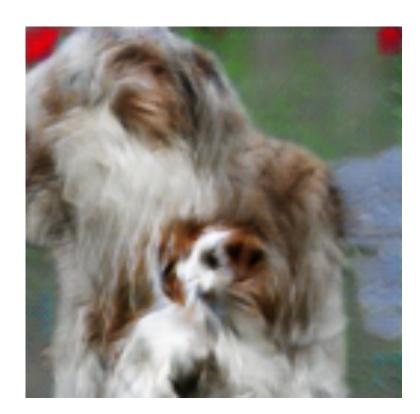
Minibatch GAN on ImageNet

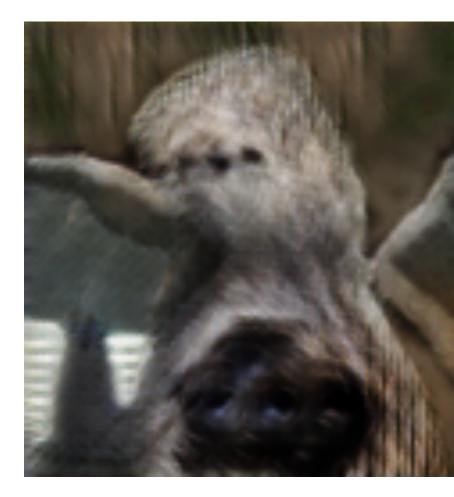


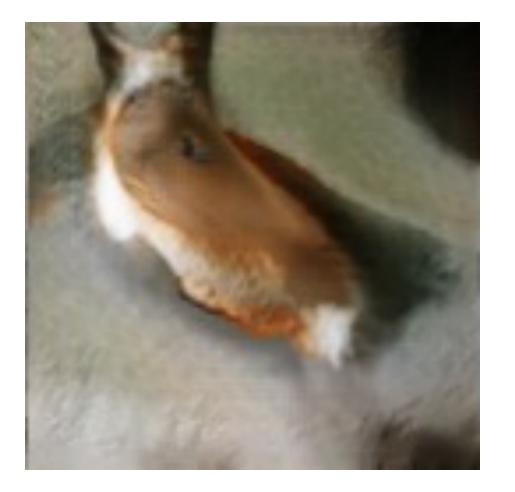
(Salimans et al., 2016)

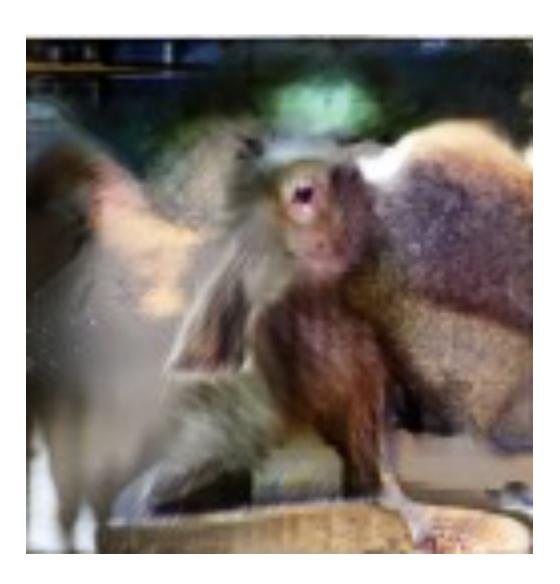


Cherry-Picked Results



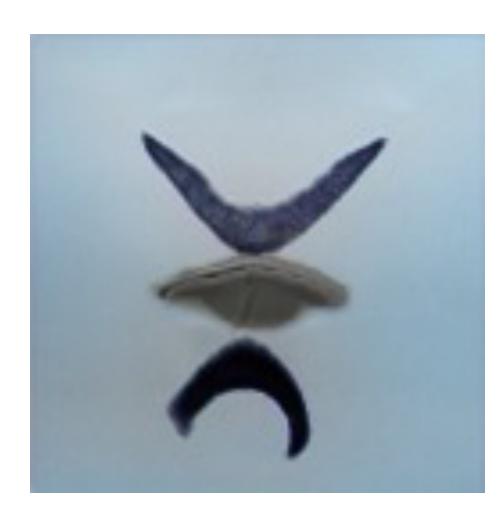






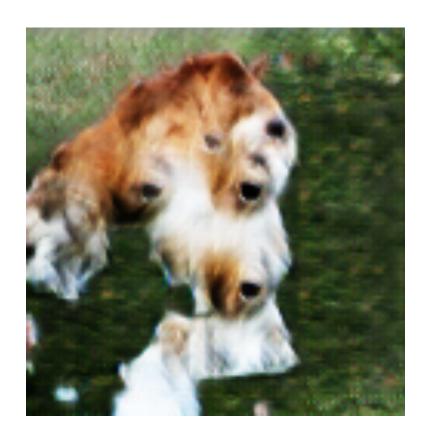






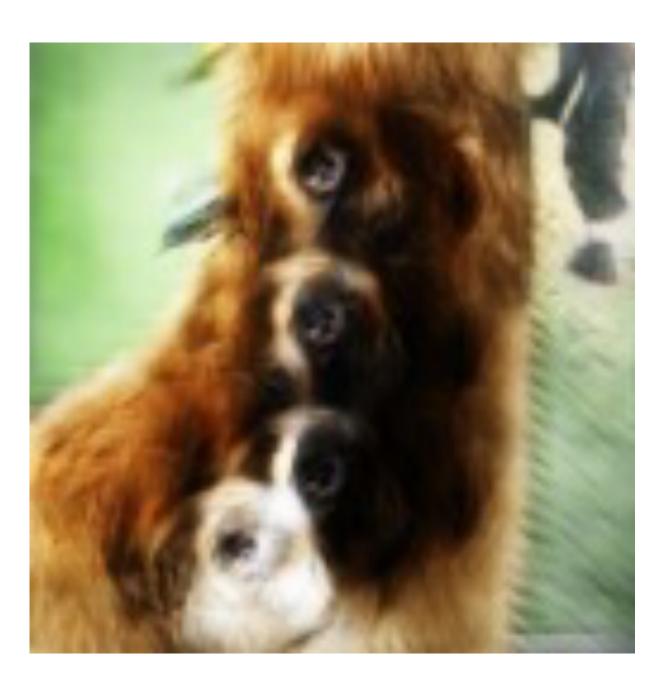


Problems with Counting











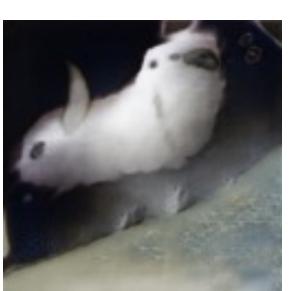


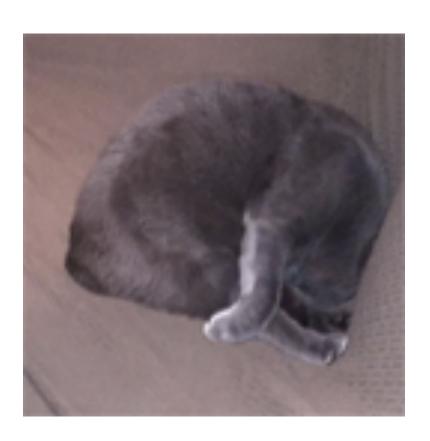




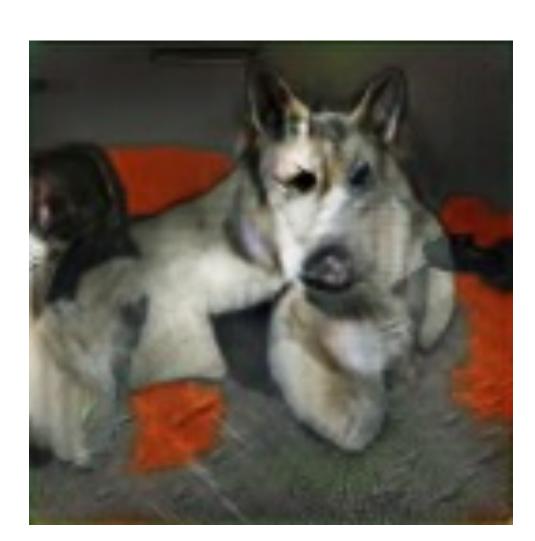
Problems with Perspective





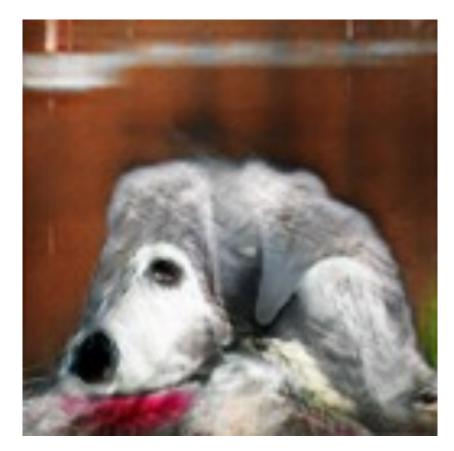




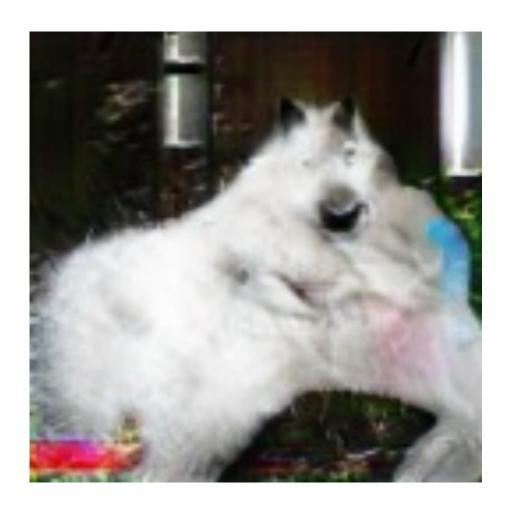


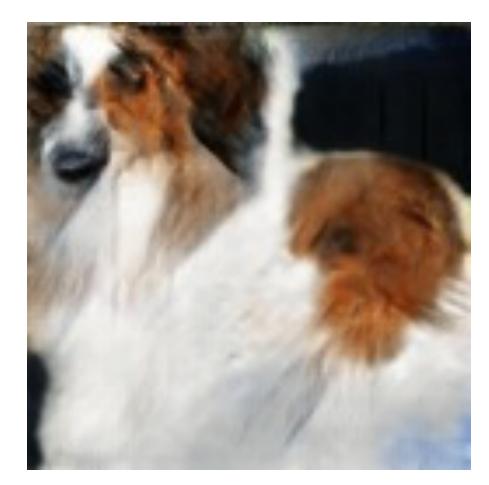


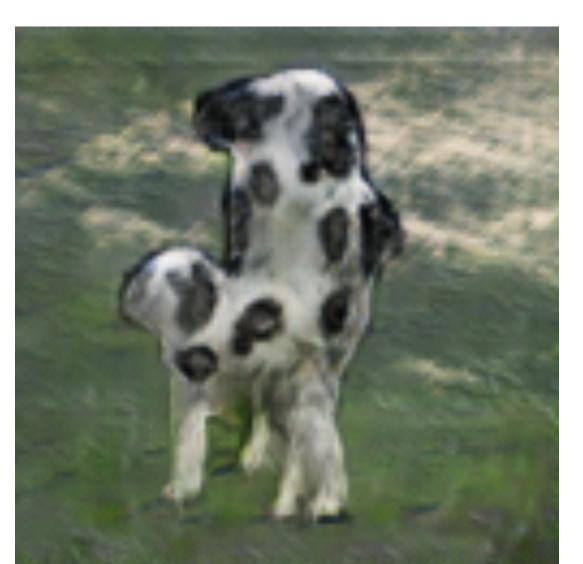














Problems with Global

Structure

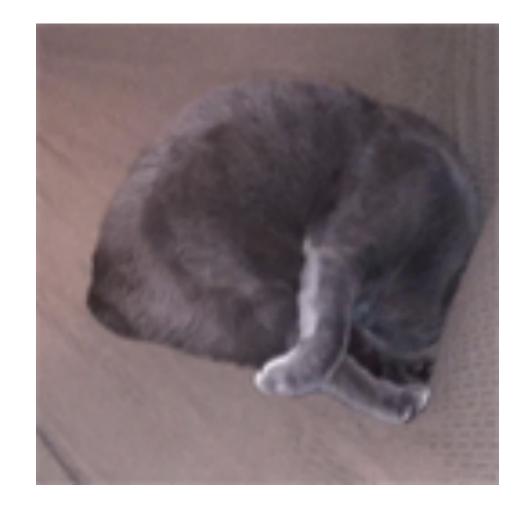








This one is real





Conclusion

- tasks
- before GANs can generate arbitrary data

• GANs are generative models based on game theory

• GANs open the door to a wide range of engineering

• There are still important research challenges to solve

