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Physics Based Sensor simulation

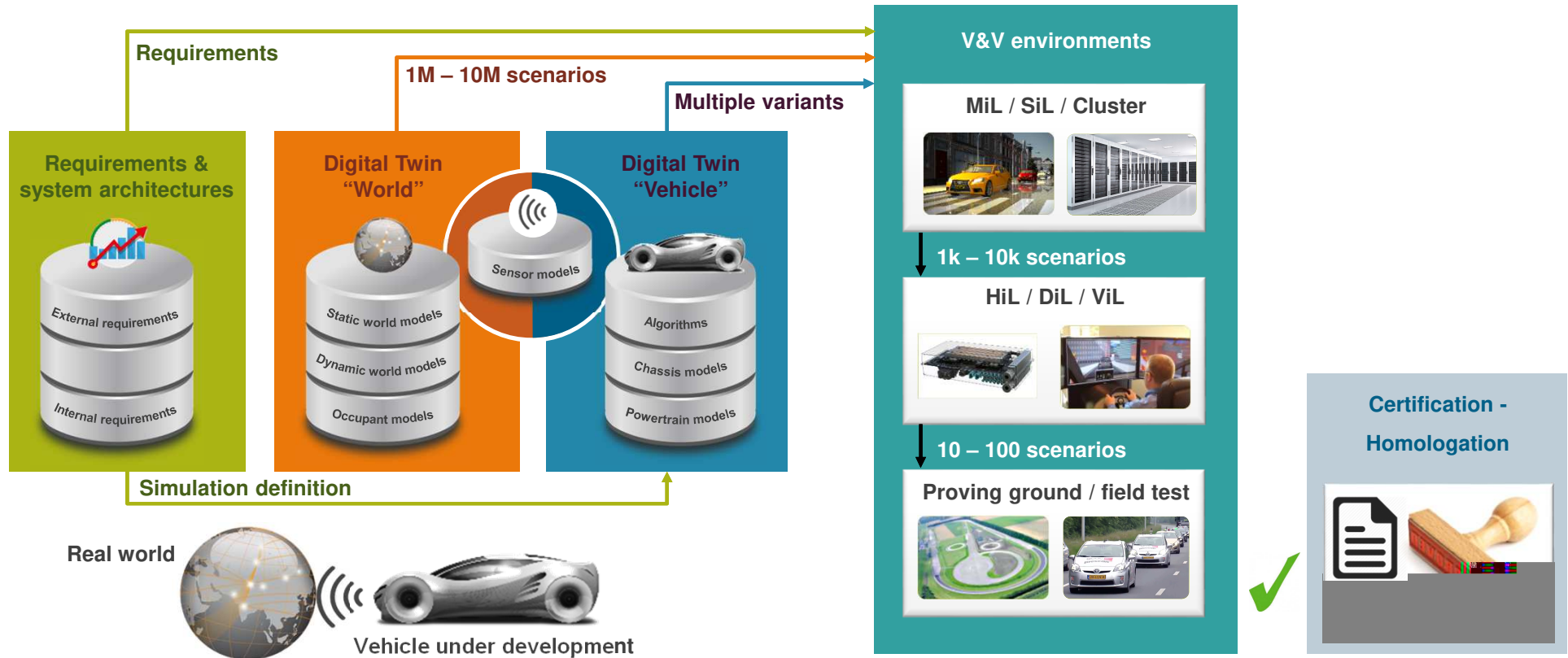
Jordan Gorrochotegui - Product Manager

Mike Phillips – Software Engineer

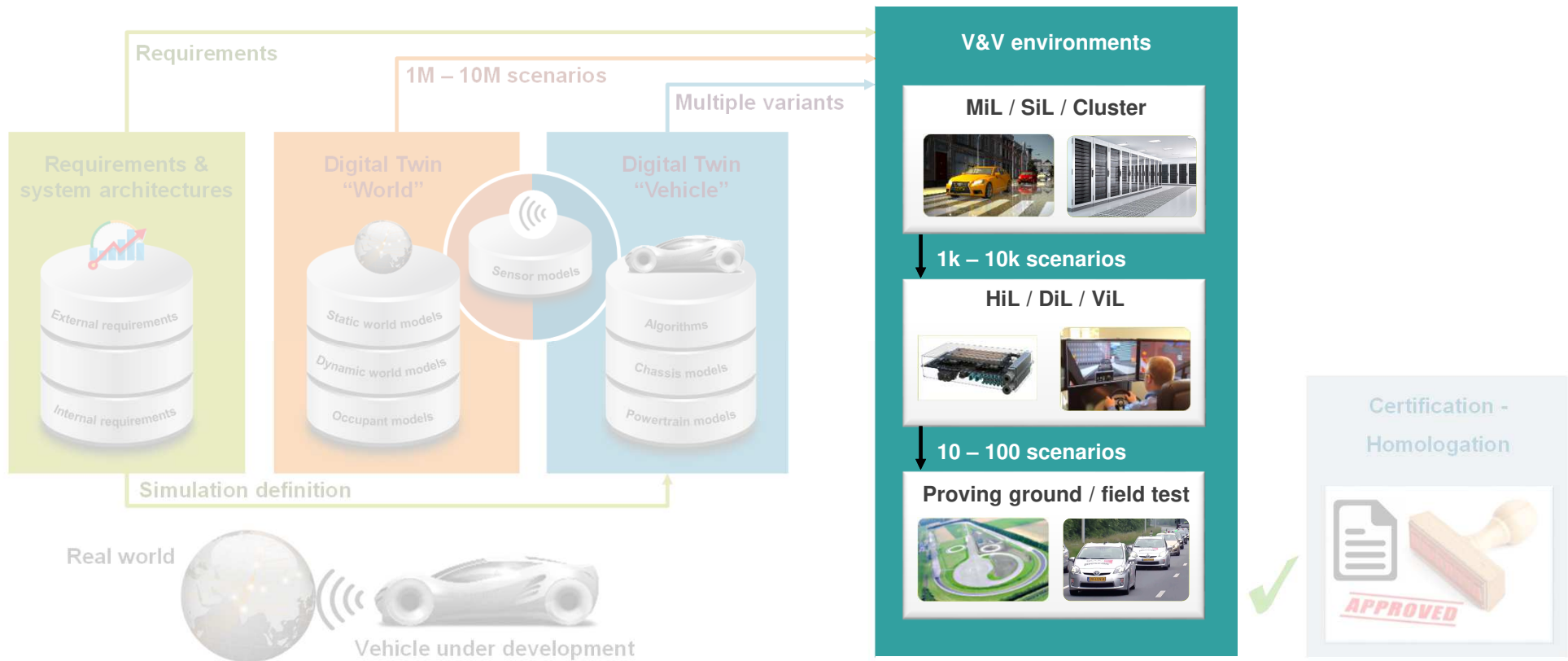
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Realize innovation.

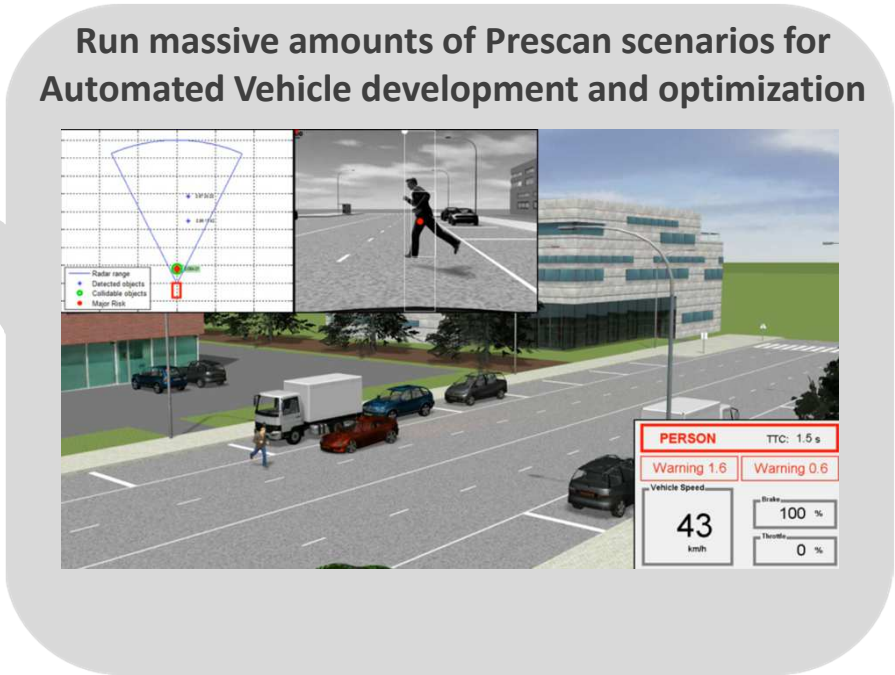
Validation and Verification framework for AVs



Validation and Verification framework for AVs

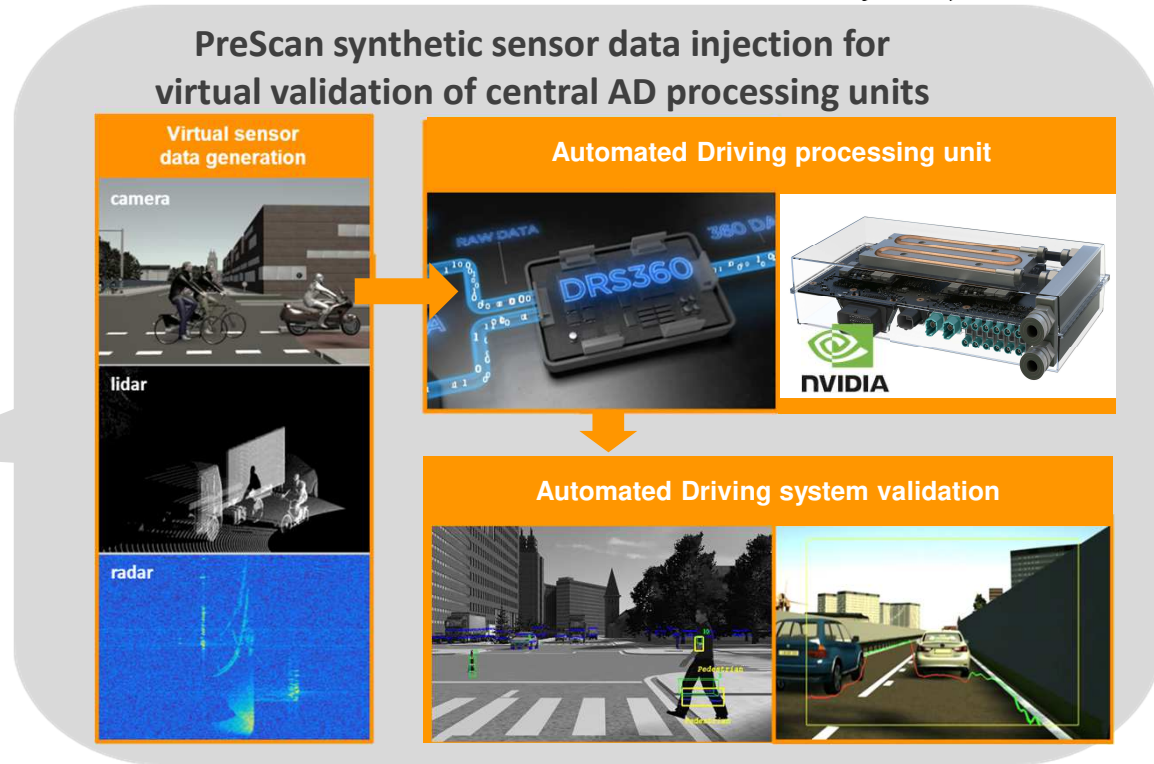
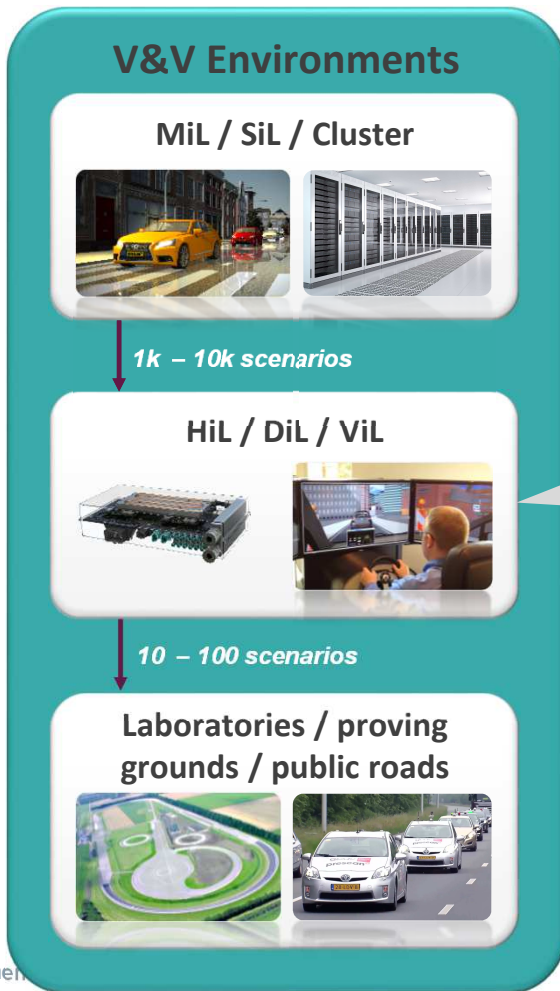


Example #1: MiL / SiL / Cluster



- Design space exploration using large scenario databases
- Virtual development, verification and robustness testing
- Optimized automated vehicle designs
- Training of Deep Neural Networks (DNNs)

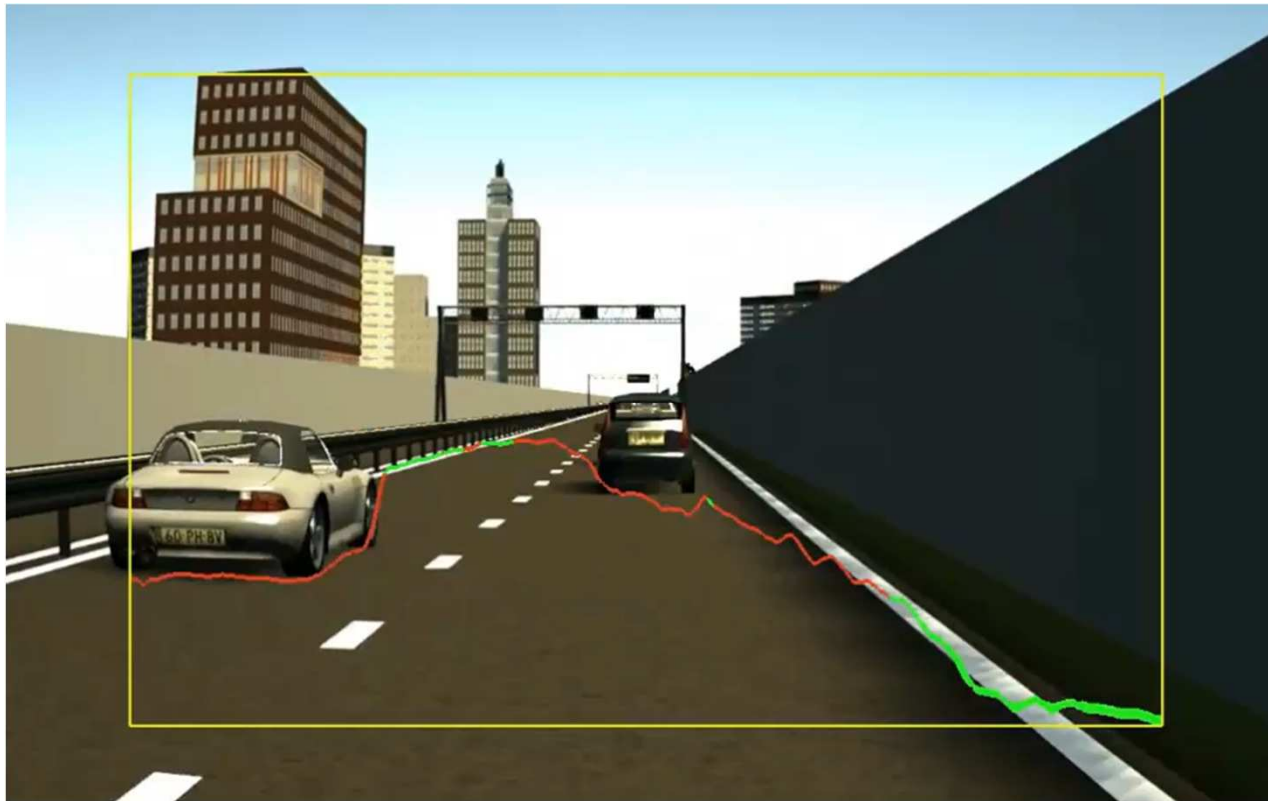
Example #2: HiL testing of central AD processing unit



- Evaluation of Deep Neural Networks (DNNs)
- Virtual validation of automated driving processing units
- Accelerated automated vehicle development

Example #2: HiL testing of central AD processing unit

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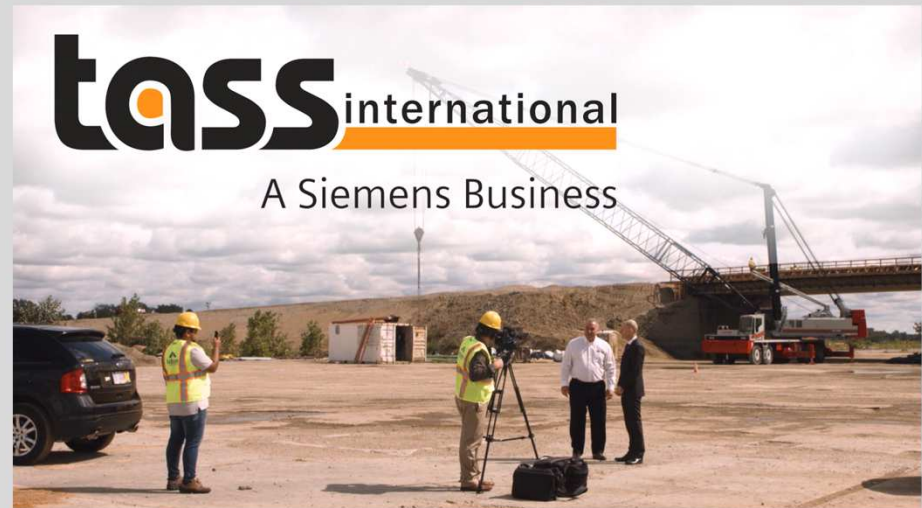
Free space detection on Nvidia Drive PX2



Example #3: Automated Driving physical validation

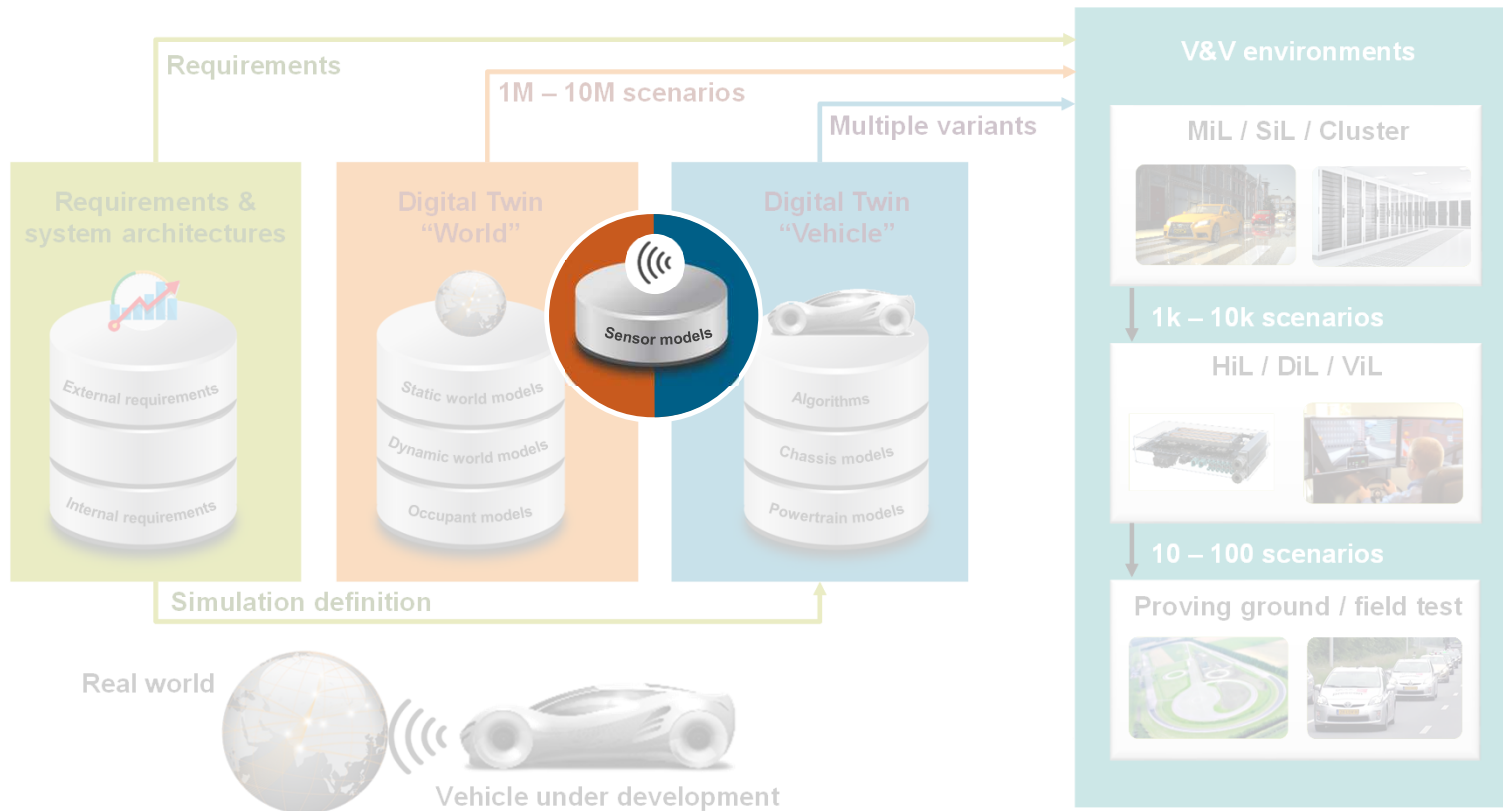


TASS International Services and Siemens Testing Solutions for physical validation of automated and connected driving technology



- Physical verification & validation services
- Certification of automated and connected systems
- Design consultancy for “next-generation” AD test facilities

Validation and Verification framework for AVs



Two sources of sensor data

- + **Real data**
- Expensive
- Time consuming
- Not (easily) repeatable
- Requires a physical sensor
- Must be annotated

Recorded

- ? Realistic data
- + **Inexpensive**
- + **Fast to acquire**
- + **Perfect repeatability**
- + **Physical sensor not needed**
- + **Annotation is free**

Simulated

We use simulation to compute real world effects on actual sensors

Physical artefacts are faithfully reproduced

- Distortions
- Multi-bounce
- Time effects
- Weather
- ...

Raw signal is computed

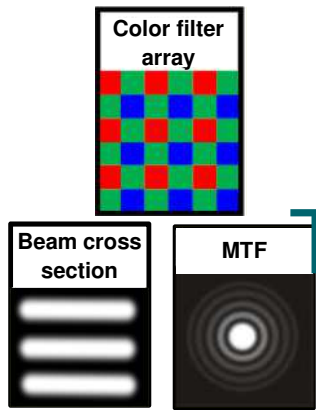
- Lidar full-waveform signal
- Radar channel response
- Raw camera images
- ...

Output verified & validated

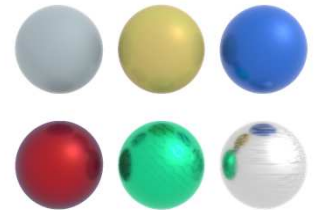
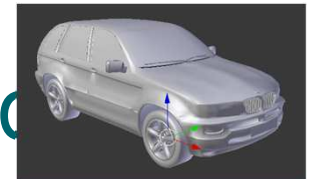
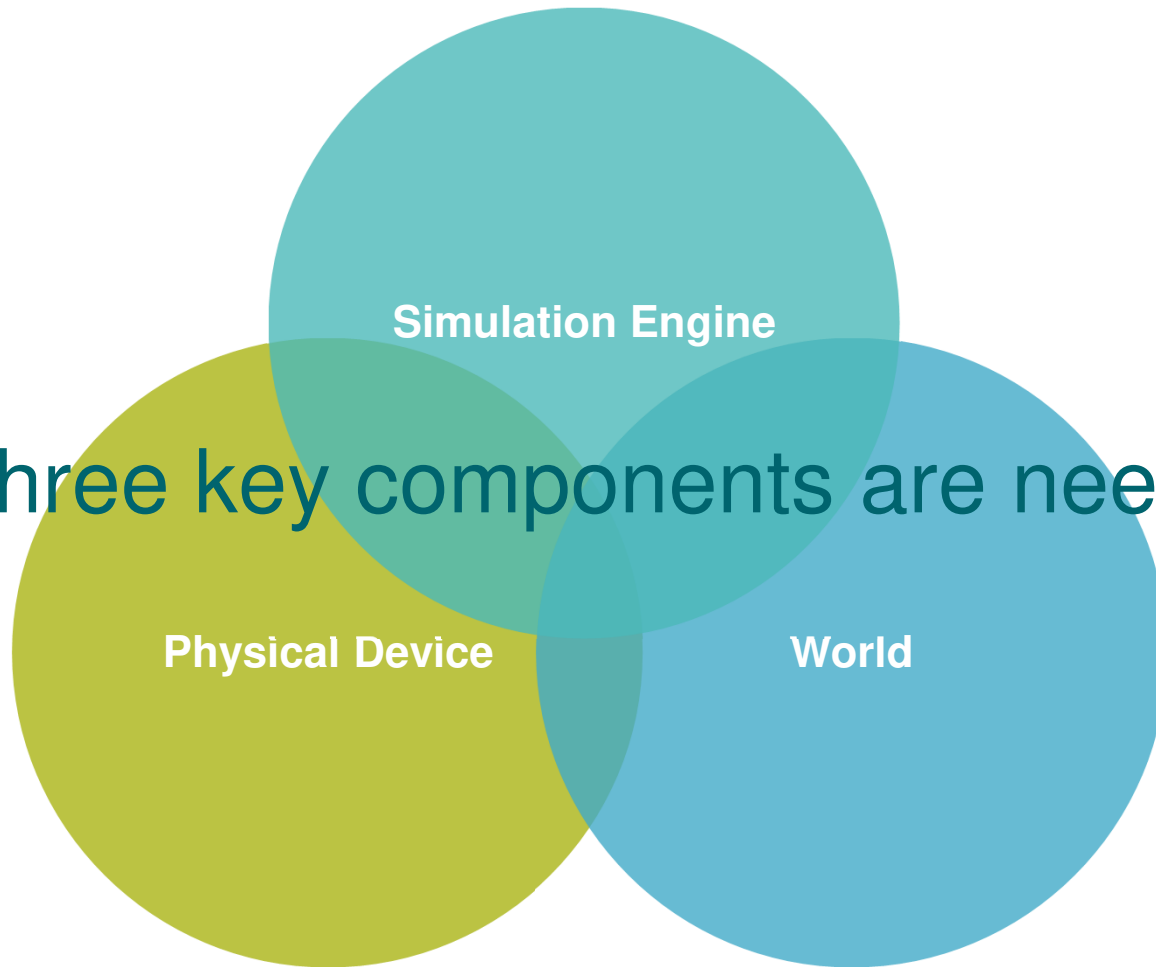
- Verify against real sensors
- Validate for specific use cases

prescan®

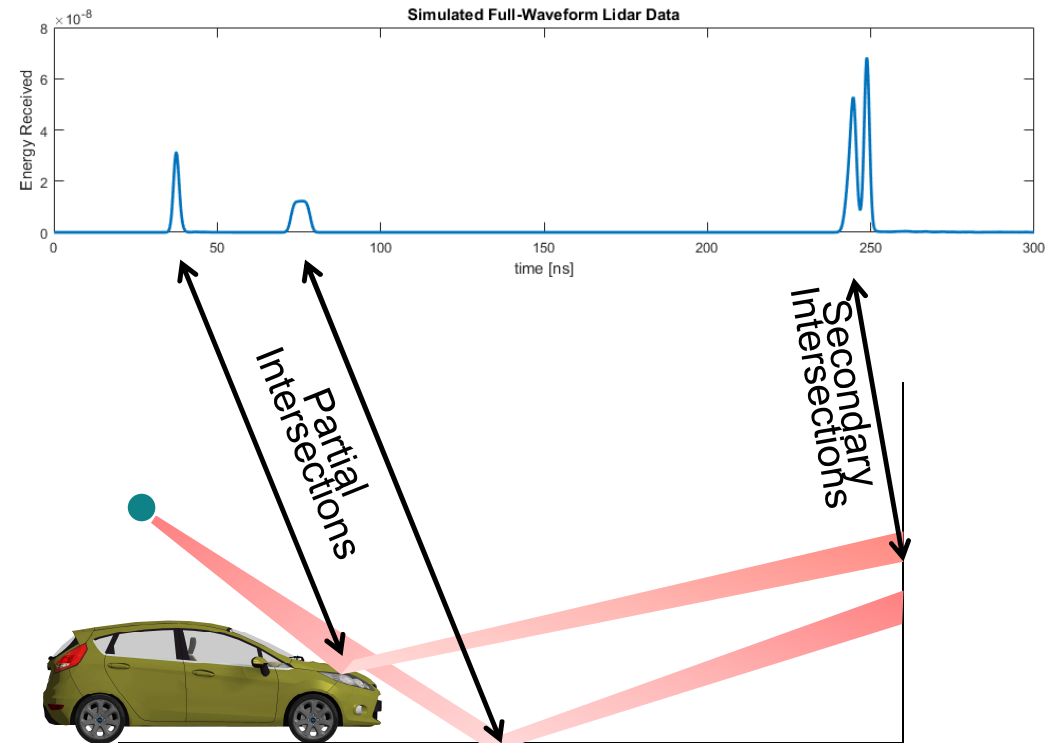
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Three key components are needed



Physics Based Lidar Simulation



A 3D rendered city street scene. On the left, there are multi-story brick buildings with many windows and red doors. A street with white lane markings runs through the center. Several cars are on the road: a white car on the left, a red Toyota Prius in the middle, a blue Audi sedan in the middle, and a dark grey SUV on the right. In the background, a white truck is parked. A tall, thin light pole stands on the right side of the street. A white rectangular sign is attached to the pole, featuring the Siemens logo and tagline.

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Thank You

Jordan Gorrochotegui - Product Manager

Mike Phillips – Software Engineer